Electric Adaptive Grippers EAG2-73105 2-Finger

- Slim body with one installation positions
 Grip control: force and position adjustment
 Quick open/close time with speed adjustment
 Grip feedback and part detection: gripper status can be read at the PLC/Controller and visualized on the unit via LED's
 Plug and play: mechanical and software interface for major cobot manufacturers

 * Multiple communication modes: the gripper supports Modeus PTLI protocol and IO is a support of the protocol and IO is a support of the gripper supports.
- Multiple communication modes: the gripper supports Modbus RTU protocol and IO mode control. Other protocols such as USB and ETHERNET can be implemented through a protocol converter.
 Grip actuation via embedded controller.
 Brake locking mechanism.



SPECIFICATIONS

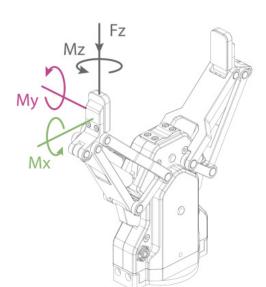
Model	Stroke	Gripping Force per Jaw	Total Gripping Force	Opening/ Closing Time	Nominal Voltage	Nominal Current		Repeatability (Positioning)	Recommended Workpiece Weight*	Weight (fingers excluded)
EAG2-73105	145 mm	35 - 105 N	70 - 210 N	0.7 / 0.7 s 24 V	24 V DC + 100/	0.8 A	1.50 A	± 0.03 mm	2.00 kg	1.30 kg
EAG2-73105	5.71 in	7.87 - 23.60 lb	15.74 - 47.21 lb		24 V DC ± 10%			± 0.001 in	4.41 lb	2.87 lb

^{*} Recommended workpiece weight depends on the shape of the part, the material and friction of the contact surface and the acceleration of the motion.

Communication Interface Standard: Modbus RTU (RS485), Digital I/O Optional: TCP/IP, USB2.0, CAN2.0A, PROFINET, EtherCAT

IP Protection Class IP 54

Noise Emission (Sound Pressure) ≤ 40 dB(A) in any direction Recommended operating environment 0-40 °C (32-104 °F), < 85% RH

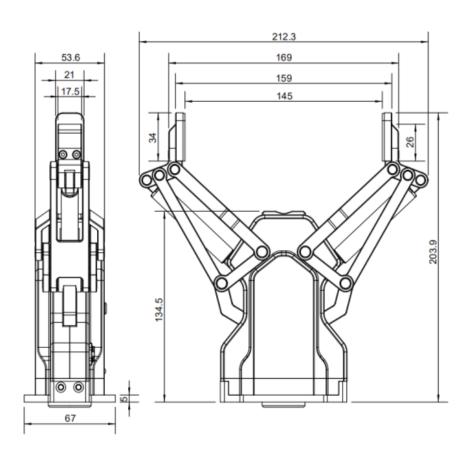


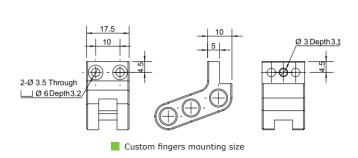
Allowable vertical load (static)								
Fz	300 N (67.44 lb)							
Allowable moment (static)								
Mx	1.95 Nm (17.26 in-lb)							
Му	1.95 Nm (17.26 in-lb)							
Mz	1.95 Nm (17.26 in-lb)							

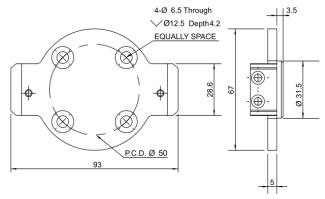


PRODUCT INFORMATION

EAG2-73105 2-Finger







Conform to ISO 9409-1-50-4-M6 standard flange



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