Collaborative Parallel Grippers ECG2-30300 2-Finger

- ECG is a collaborative 2-finger parallel gripper triat is equipped with symmetry.
 Advantages
 Compact design
 Smooth body with rounded edges ideal for collaborative applications
 Grip control: force and position adjustment
 Quick open/close time with speed adjustment
 Grip feedback and part detection: gripper status can be read at the PLC/Controller and visualized on the unit via LED's
 Plug and play: mechanical and software interface for major cobot manufacturers
 Multiple communication modes: the gripper supports Modbus RTU protocol and IO mode control. Other protocols such as USB and ETHERNET can be implemented through a protocol converter.
 ROS compatible

- ROS compatible
 Designed for harsh environments
 Grip actuation via embedded controller.
 Brake locking mechanism.



SPECIFICATIONS

| Model | Stroke per Jaw | Gripping Force per Jaw | Total Gripping Force | Opening/ Closing Time | Nominal Voltage | Nominal Current | | Repeatability (Positioning) | Recommended Workpiece Weight* | Weight |
|------------|-------------------|------------------------------|-------------------------|-----------------------------|--------------------|--------------------|--------|--------------------------------|-------------------------------------|---------|
| ECG2-30300 | 30 mm | 40 - 300 N | 80 - 600 N | 0.8 / 0.8 s | 24 V DC ± 10% | 0.40 A | 2.00 A | ± 0.03 mm | 6.0 kg | 1.50 kg |
| | 1.18 in | 8.99 - 67.44 lb | 17.98 - 134.89 lb | | | | | ± 0.001 in | 13.23 lb | 3.31 lb |

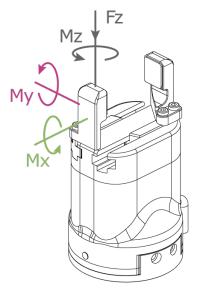
^{*} Recommended workpiece weight depends on the shape of the part, the material and friction of the contact surface and the acceleration of the motion.

Communication Interface Standard: Modbus RTU (RS485), Digital I/O
Optional: TCP/IP, USB2.0, CAN2.0A, PROFINET, EtherCAT

IP Protection Class IP 67

Noise Emission (Sound Pressure) ≤ 40 dB(A) in any direction Recommended operating environment 0-40 °C (32-104 °F), < 85% RH

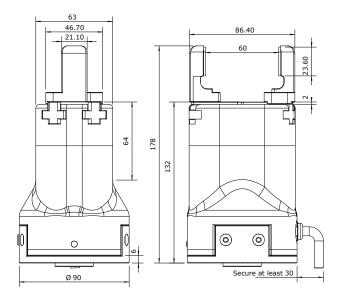
For this type of gripper the use of the standard fingers is recommended.

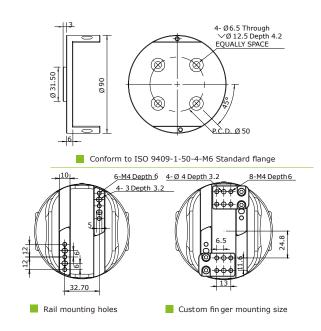


| Allowable vertical load (static) | | | | | | | | |
|----------------------------------|----------------------|--|--|--|--|--|--|--|
| Fz | 600 N (134.89 lb) | | | | | | | |
| Allowable moment (static) | | | | | | | | |
| Mx | 15 Nm (132.76 in-lb) | | | | | | | |
| Му | 15 Nm (132.76 in-lb) | | | | | | | |
| Mz | 15 Nm (132.76 in-lb) | | | | | | | |
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ECG2-30300 2-Finger







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