

Electric Parallel Grippers

EIG2-13050 2-Finger

EIG is an electric 2-finger parallel gripper that is equipped with two symmetrically parallel fingers.

Advantages

- Compact size
- Slim rectangular body with five installation positions for flexible mounting
- Grip control: force and position adjustment
- Quick open/close time with speed adjustment
- Grip feedback and part detection: gripper status can be read at the PLC/Controller and visualized on the unit via LED's
- Multiple communication modes: the gripper supports Modbus RTU protocol and IO mode control. Other protocols such as USB and ETHERNET can be implemented through a protocol converter.
- Grip actuation via embedded controller.
- Brake locking mechanism on request.



SPECIFICATIONS

Model	Stroke per Jaw	Gripping Force per Jaw	Total Gripping Force	Opening / Closing Time	Nominal Voltage	Nominal Current	Max Current	Repeatability (Positioning)	Recommended Workpiece Weight*	Weight
EIG2-13050	13 mm 0.51 in	15 - 50 N 3.37 - 11.24 lb	30 - 100 N 6.74 - 22.48 lb	0.3 / 0.3 s	24 V DC $\pm$ 10%	0.25 A	0.50 A	$\pm$ 0.02 mm $\pm$ 0.001 in	1.00 kg 2.20 lb	0.40 kg 0.88 lb

* Recommended workpiece weight depends on the shape of the part, the material and friction of the contact surface and the acceleration of the motion.

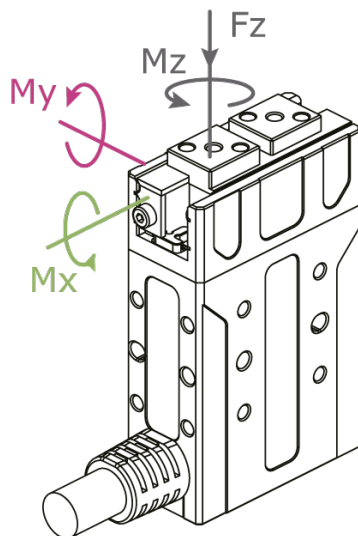
Communication Interface **Standard: Modbus RTU (RS485), Digital I/O**
Optional: TCP/IP, USB2.0, CAN2.0A, PROFINET, EtherCAT

IP Protection Class **IP 40**

Noise Emission (Sound Pressure) $\leq$ **40 dB(A) in any direction**

Recommended operating environment **0-40 °C (32-104 °F), < 85% RH**

For this type of gripper the use of the standard fingers is recommended.



Allowable vertical load (static)

Fz 150 N (33.72 lb)

Allowable moment (static)

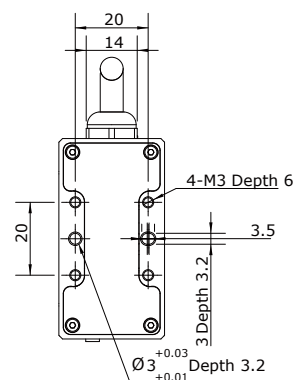
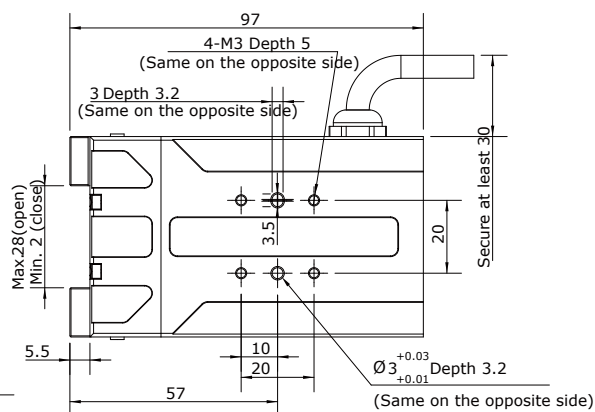
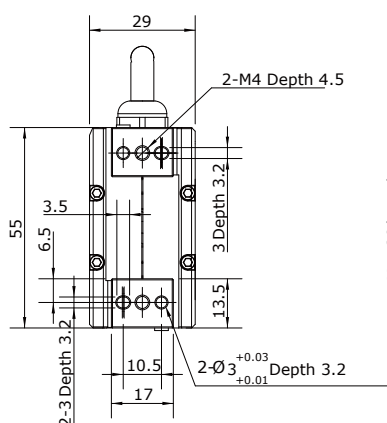
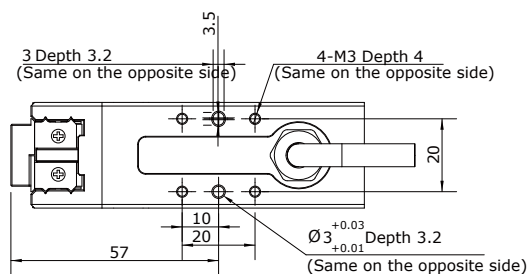
Mx 2.5 Nm (22.13 in-lb)

My 2.0 Nm (17.70 in-lb)

Mz 3.0 Nm (26.55 in-lb)

PRODUCT INFORMATION

EIG2-13050 2-Finger



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