Electric Actuator

Series LEL

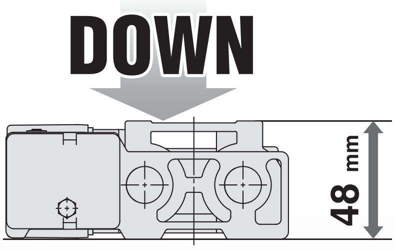
Guide Rod Slider

Step Motor (Servo/24 VDC)

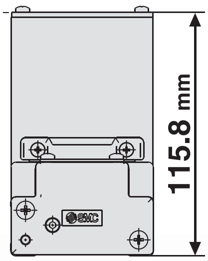
LEFS LEFB
LEJS LEJB
LEL
LEM
LEY LEYG
LES LESH
LEPY LEPS
LER
LEH
LEY-X5
11-LEFS
11-LEJS
25A-
LEC□
LECS□
LECSS-T
LECYM LECYU
Motorless
LAT3

Low-profile/Flat **Height 48 mm**

Profile reduced by side mounting of motor



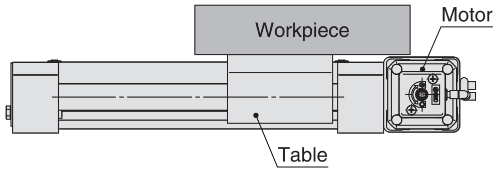
LEL25

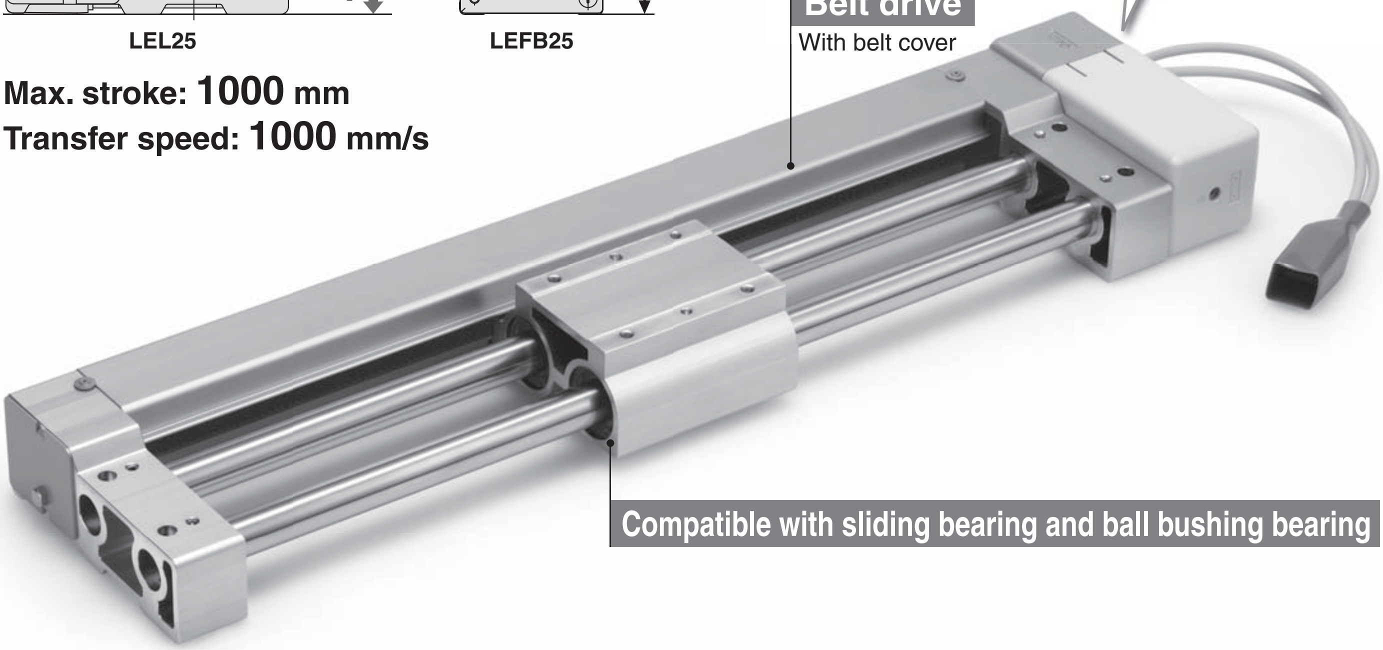


LEFB25

Max. stroke: 1000 mm
Transfer speed: 1000 mm/s

No interference with motor, even with large workpieces!





Model	Size	Bearing	Stroke [mm]	Work load (Horizontal) [kg]	Speed [mm/s]	Positioning repeatability [mm]	Page
LEL25M	25	Sliding bearing	Up to 1000	3	Up to 500	±0.08	▸Page 143
LEL25L		Ball bushing bearing	Up to 1000	5	Up to 1000	±0.08	

Step Motor (Servo/24 VDC) **Controller**

▸Page 538

▸Step data input type
Series LECP6
- 64 points positioning
- Input using controller setting kit or teaching box

▸CC-Link direct input type
*Series LECPMJ**

* Not applicable to CE.

▸Programless type
Series LECP1
- 14 points positioning
- Control panel setting

Step Motor (Servo/24 VDC) **Type**

Guide Rod Slider **Size: 25**

Simple construction.
Guide type can be selected.

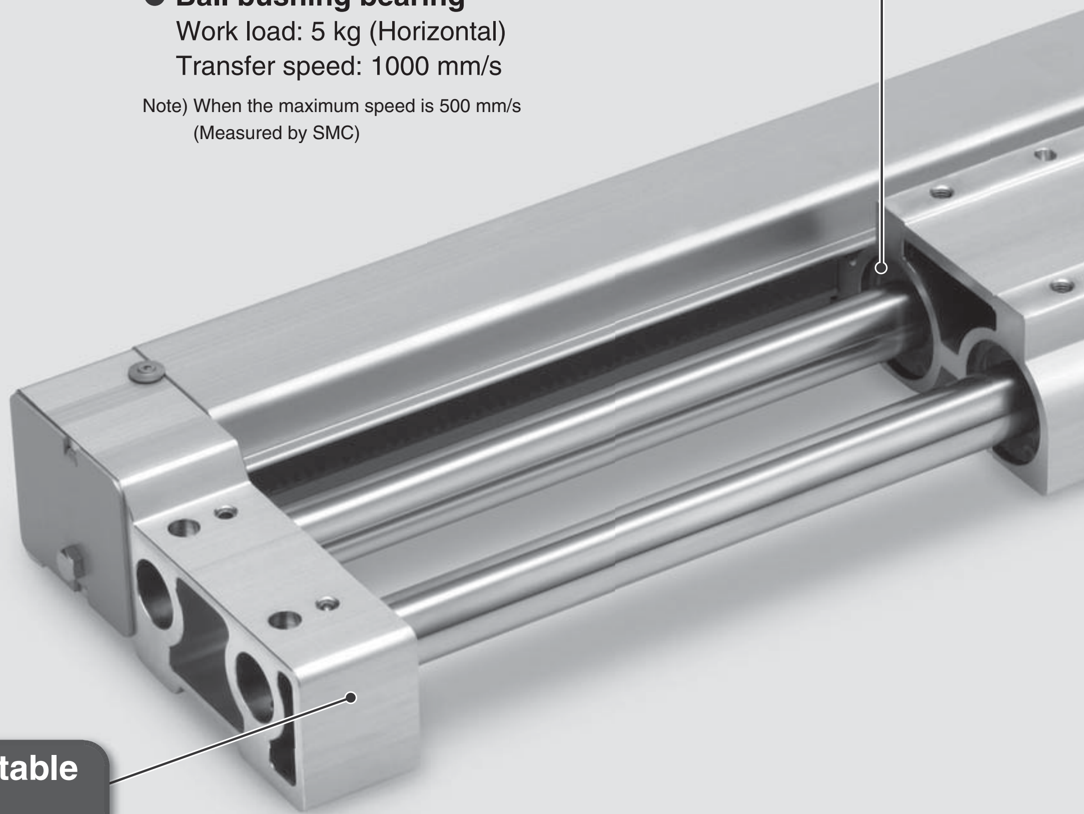
Max. stroke: 1000 mm

Transfer speed: 1000 mm/s

Guide type

- **Sliding bearing**
  Work load: 3 kg (Horizontal)
  Reduced noise (60 dB or less) Note)
- **Ball bushing bearing**
  Work load: 5 kg (Horizontal)
  Transfer speed: 1000 mm/s

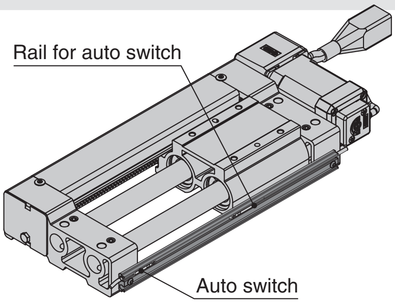
Note) When the maximum speed is 500 mm/s
(Measured by SMC)



Auto switch mountable
(Made to Order)

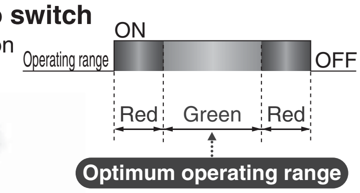
For checking the limit and intermediate signal
Applicable to the D-M9□ and D-M9□W (2-color indication)

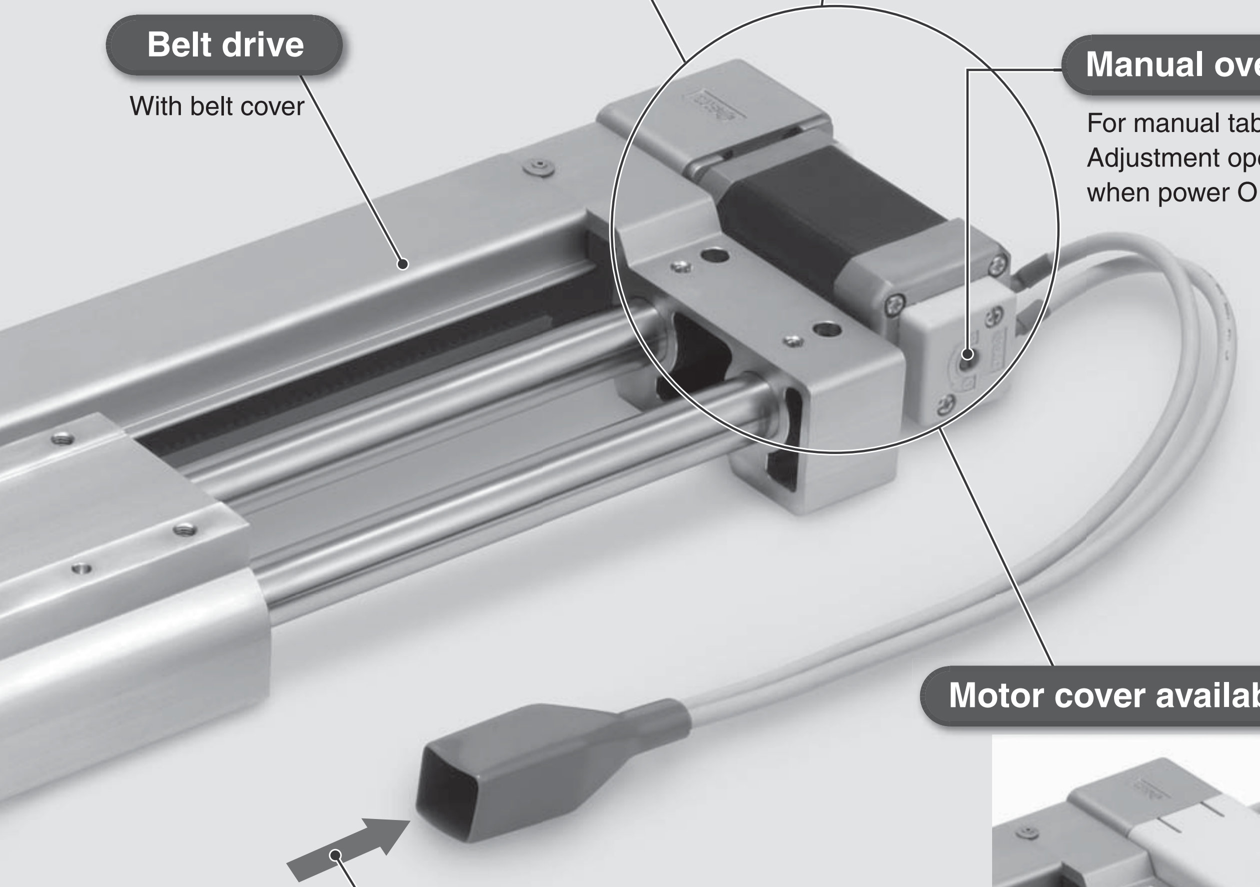
∗ The auto switches should be ordered separately. Refer to pages 152 and 153 for details.



2-color indication solid state auto switch
Appropriate setting of the mounting position can be performed without mistakes.

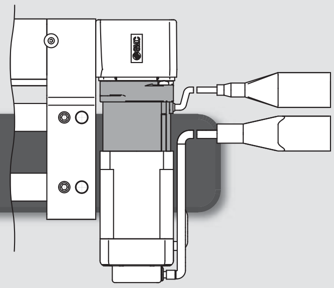
A green light lights up at the optimum operating range.





Compatible motor
Step motor (Servo/24 VDC)

Non-magnetizing lock (Option)
Holding a workpiece



Belt drive
With belt cover

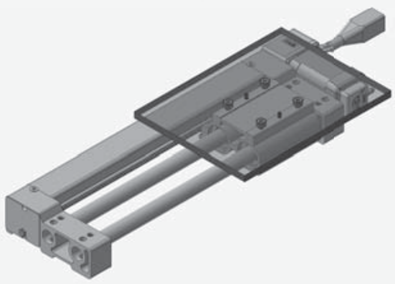
Manual override screw
For manual table operation.
Adjustment operation possible when power OFF

Motor cover available (Option)

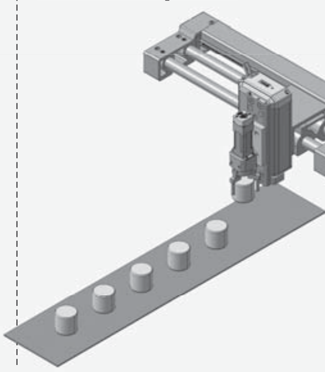
Offering 2 types of actuator cables
- Standard cable
- Robotic cable (Flexible cable)

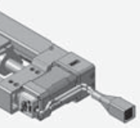
Application Examples

Load and unload transfer of workpieces

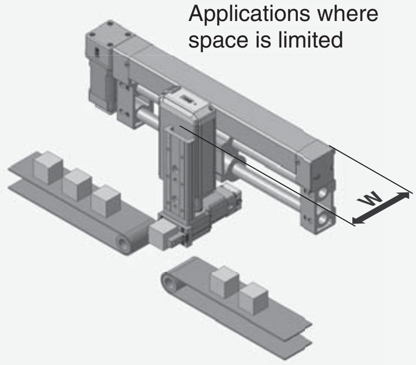


Pick and place





Applications where space is limited



Step Motor (Servo/24 VDC)

Electric Actuator/Guide Rod Slider *Series* ***LEL***

Step Motor (Servo/24 VDC) Controller

Guide Rod Slider

Series LEL

Step Motor (Servo/24 VDC)

LEFS LEFB
LEJS LEJB
LEL
LEM
LEY LEYG
LES LESH
LEPY LEPS
LER
LEH
LEY-X5
11-LEFS
11-LEJS
25A-
LEC□
LECS□
LECSS-T
LECYM LECYU
Motorless
LAT3

Step Motor (Servo/24 VDC)

Electric Actuator/Guide Rod Slider

Series LEL

Model Selection

Series LEL ▶ Page 147

Selection Procedure

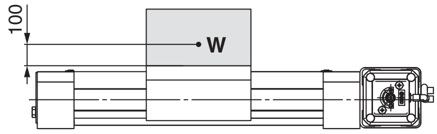
Step 1 Check the work load–speed. → **Step 2** Check the cycle time. → **Step 3** Check the allowable moment.

Selection Example

Operating conditions

- Workpiece mass: 4 [kg]
- Speed: 300 [mm/s]
- Acceleration/Deceleration: 3000 [mm/s^2]
- Stroke: 500 [mm]
- Mounting position: Horizontal upward

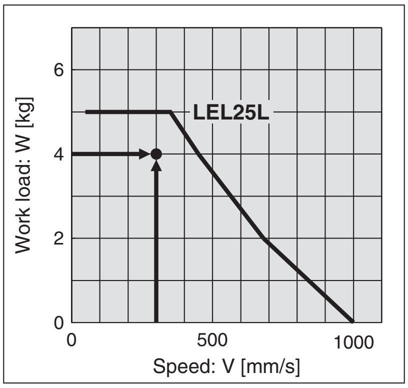
- Workpiece mounting condition:



Step 1 Check the work load–speed. <Speed–Work load graph> (Page 146)

Select the target model based on the workpiece mass and speed with reference to the <Speed–Work load graph>.

Selection example) The **LEL25LT-500** is temporarily selected based on the graph shown on the right side.



<Speed–Work load graph>
(LEL25L/Step motor)

Step 2 Check the cycle time.

Calculate the cycle time using the following calculation method.

Cycle time:

T can be found from the following equation.

$\boxed{T = T1 + T2 + T3 + T4 \text{ [s]}}$

- T1: Acceleration time and T3: Deceleration time can be obtained by the following equation.

  $\boxed{T1 = V/a1 \text{ [s]}}$ $\boxed{T3 = V/a2 \text{ [s]}}$

- T2: Constant speed time can be found from the following equation.

  $$\boxed{T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} \text{ [s]}}$$

- T4: Settling time varies depending on the conditions such as motor types, load and in position of the step data. Therefore, please calculate the settling time with reference to the following value.

  $\boxed{T4 = 0.3 \text{ [s]}}$

Calculation example)
T1 to T4 can be calculated as follows.

$T1 = V/a1 = 300/3000 = 0.1$ [s],

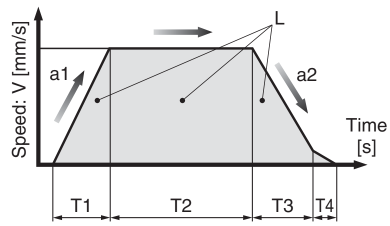
$T3 = V/a2 = 300/3000 = 0.1$ [s]

$$T2 = \frac{L - 0.5 \cdot V \cdot (T1 + T3)}{V} = \frac{500 - 0.5 \cdot 300 \cdot (0.1 + 0.1)}{300} = 1.57 \text{ [s]}$$

$T4 = 0.3$ [s]

Therefore, the cycle time can be obtained as follows.

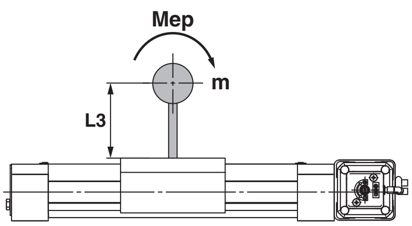
$T = T1 + T2 + T3 + T4$
$= 0.1 + 1.57 + 0.1 + 0.3$
$= \mathbf{2.07}$ **[s]**

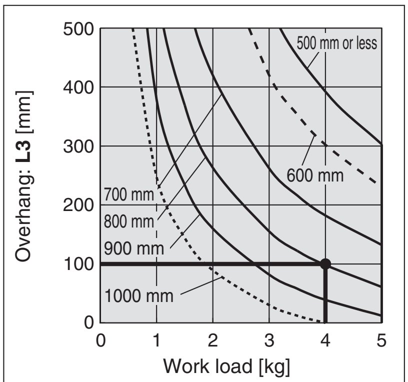


L : Stroke [mm]
···(Operating condition)
V : Speed [mm/s]
···(Operating condition)
a1: Acceleration [mm/s^2]
···(Operating condition)
a2: Deceleration [mm/s^2]
···(Operating condition)

T1: Acceleration time [s]
Time until reaching the set speed
T2: Constant speed time [s]
Time while the actuator is operating at a constant speed
T3: Deceleration time [s]
Time from the beginning of the constant speed operation to stop
T4: Settling time [s]
Time until positioning is completed

Step 3 Check the guide moment.





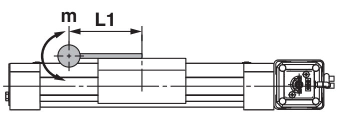
Based on the above calculation result, the LEL25LT-500 is selected.

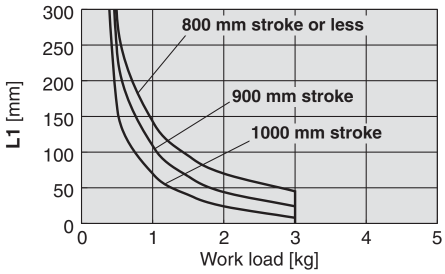
SMC

Dynamic Allowable Moment

∗ This graph shows the amount of allowable overhang (guide unit) when the center of gravity of the workpiece overhangs in one direction. When selecting the overhang, refer to “Calculation of Guide Load Factor” or the Electric Actuator Selection Software for confirmation, http://www.smcworld.com

Acceleration/Deceleration —— 3000 mm/s²

<table>
<tr><th rowspan="2">Orientation</th><th rowspan="2" colspan="2">Load overhanging direction
m: Work load [kg]
L : Overhang to the work load center of gravity [mm]</th><th colspan="2">Model</th></tr>
<tr><th>LEL25M</th><th>LEL25L</th></tr>
<tr><td rowspan="3">Horizontal/Bottom mounting</td><td>


</td><td>X</td><td>


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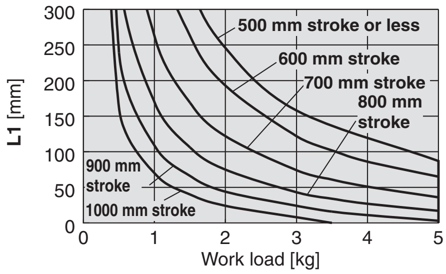

</td></tr>
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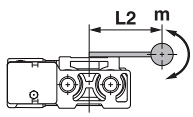
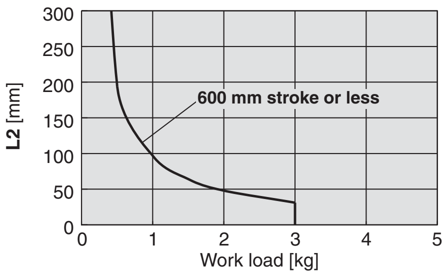


</td><td>Y</td><td>


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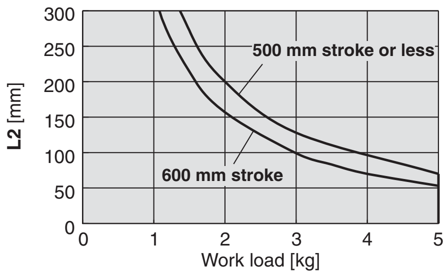

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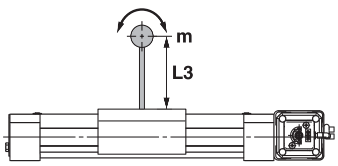
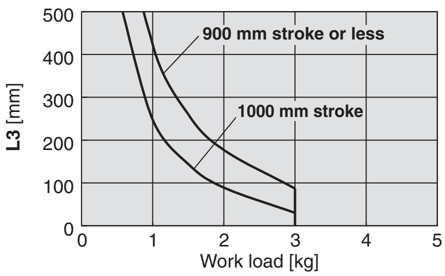
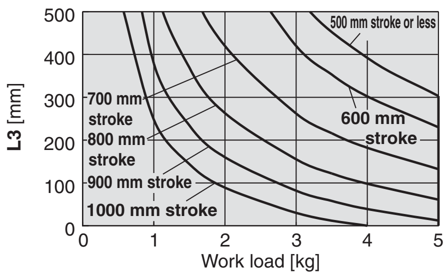


</td><td>Z</td><td>


</td><td>


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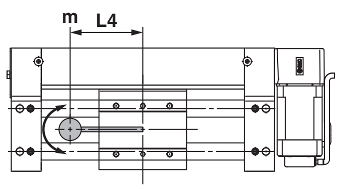
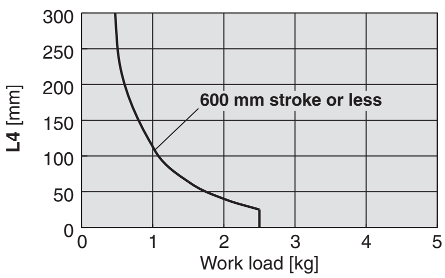
<tr><td rowspan="3">Wall mounting</td><td>


</td><td>X</td><td>


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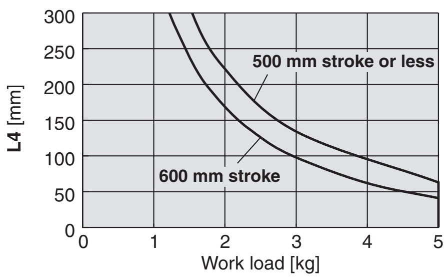

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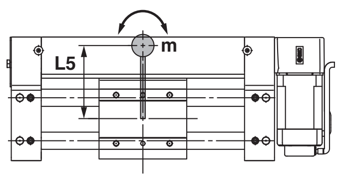
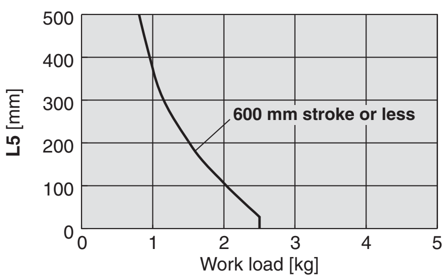


</td><td>Y</td><td>


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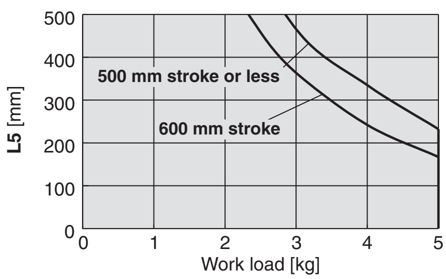

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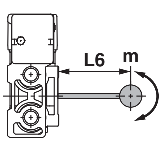
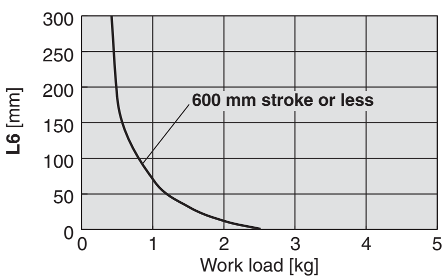


</td><td>Z</td><td>


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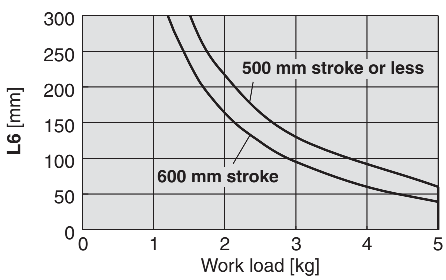
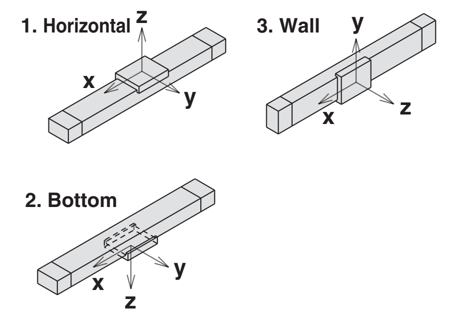


</td></tr>
</table>

Calculation of Guide Load Factor

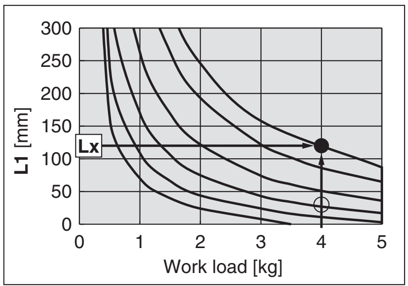
1. Decide operating conditions.
   Model: LEL
   Size: 25
   Mounting orientation: Horizontal/Bottom/Wall
   Acceleration [mm/s²]: **a**
   Work load [kg]: **m**
   Work load center position [mm]: **Xc/Yc/Zc**
2. Select the target graph with reference to the model, size and mounting orientation.
3. Based on the acceleration and work load, obtain the overhang [mm]: **Lx/Ly/Lz** from the graph.
4. Calculate the load factor for each direction.
   α**x = Xc/Lx**, α**y = Yc/Ly**, α**z = Zc/Lz**
5. Confirm the total of α**x**, α**y** and α**z** is 1 or less.
   α**x +** α**y +** α**z ≤ 1**
   When 1 is exceeded, please consider a reduction of acceleration and work load, or a change of the work load center position and series.

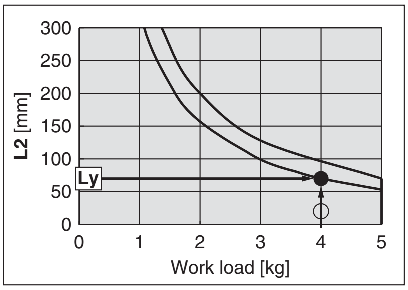
Mounting orientation

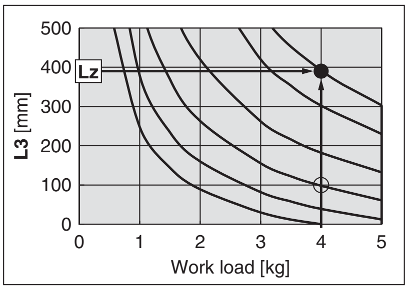


Example

1. Operating conditions
   Model: LEL
   Size: 25L
   Stroke: 500
   Mounting orientation: Horizontal
   Acceleration [mm/s²]: 3000
   Work load [kg]: 4
   Work load center position [mm]: **Xc = 30**, **Yc = 20**, **Zc = 100**
2. Select three graphs from the top of the right side on page 144.
3. **Lx = 120 mm**, **Ly = 65 mm**, **Lz = 390 mm**
4. The load factor for each direction can be obtained as follows.
   α**x = 30/120 = 0.25**
   α**y = 20/65 = 0.31**
   α**z = 100/390 = 0.26**
5. α**x +** α**y +** α**z = 0.82 ≤ 1**

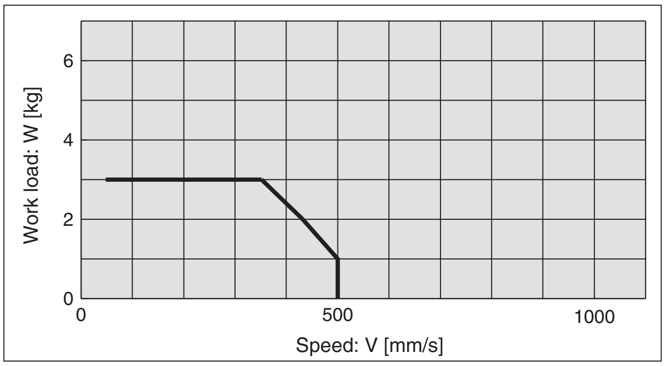






Speed–Work Load Graph (Guide)

LEL25M



LEL25L

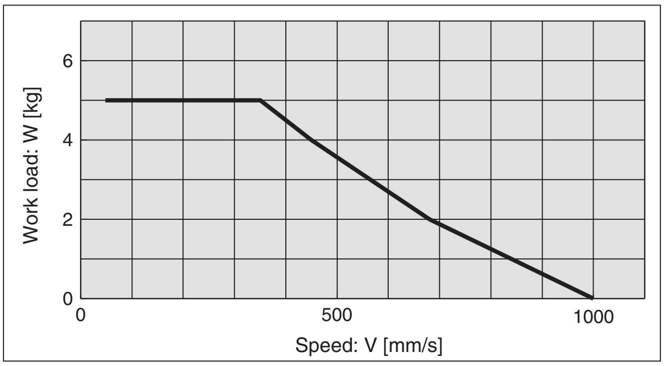
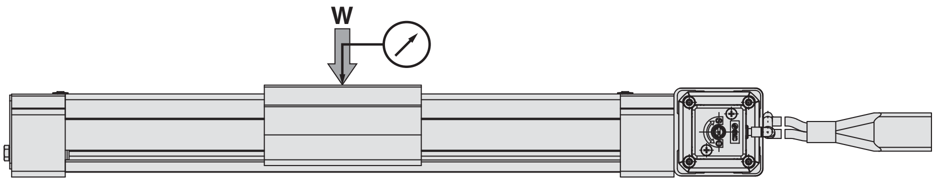
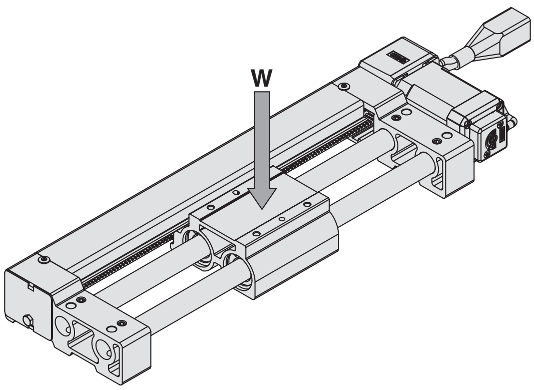


Table Displacement (Reference Value)

∗ Amount of displacement of the table when the load center of gravity is located at the table center in the middle of the stroke.





Load center of gravity located at the center of the table

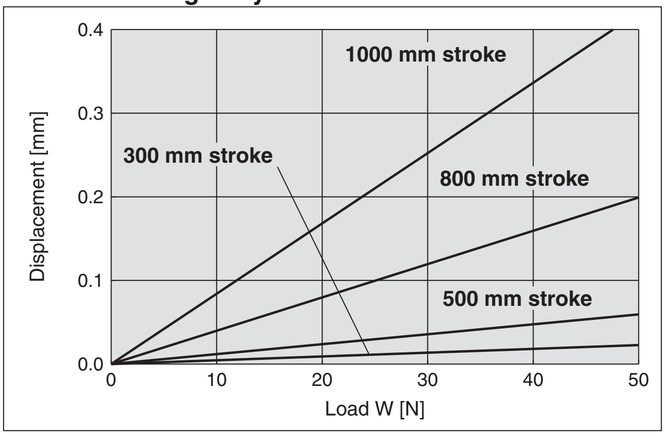
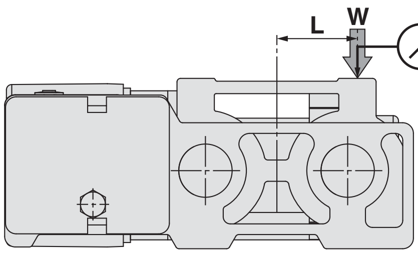
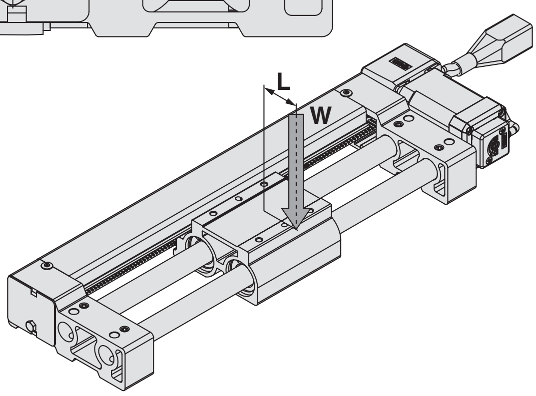


Table Displacement (Reference Value)

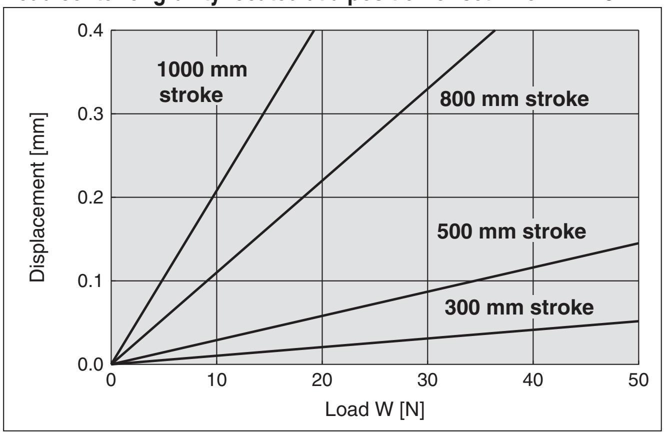
∗ Amount of displacement when the load is offset by "L" from the center of the table.



L = 25 mm



Load center of gravity located at a position offset when L = 25 mm



Step Motor (Servo/24 VDC)

Electric Actuator/Guide Rod Slider Belt Drive

Series LEL LEL25

RoHS

How to Order

LEL 25 M T – 100 □ – □ 1 6N 1 □ – □

❶ ❷ ❸ ❹ ❺ ❻ ❼ ❽ ❾ ❿ ⓫

❶ Size

25

❷ Bearing type

M	Sliding bearing
L	Ball bushing bearing

❸ Equivalent lead

T	48 mm

❹ Stroke

100	100 mm
to	to
1000	1000 mm

* Refer to the applicable stroke table.

❺ Motor option

Nil	Without option
B	With lock
C	With motor cover*

* When [With lock] is selected, [With motor cover] cannot be selected.

❻ Actuator cable type*

Nil	Without cable
S	Standard cable
R	Robotic cable (Flexible cable)

* The standard cable should be used on fixed parts. For using on moving parts, select the robotic cable.

⚠Caution

[CE-compliant products]

① EMC compliance was tested by combining the electric actuator LEL series and the controller LEC series.
The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore, conformity to the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result, it is necessary for the customer to verify conformity to the EMC directive for the machinery and equipment as a whole.

② CC-Link direct input type (LECPMJ) is not CE-compliant.

[UL-compliant products]

When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.

Applicable Stroke Table ●: Standard/○: Produced upon receipt of order

Model \ Stroke	100	200	300	400	500	600	700	800	900	1000
LEL25	○	○	●	●	●	●	○	○	○	○

* Please consult with SMC as all non-standard and non-made-to-order strokes are produced as special orders.

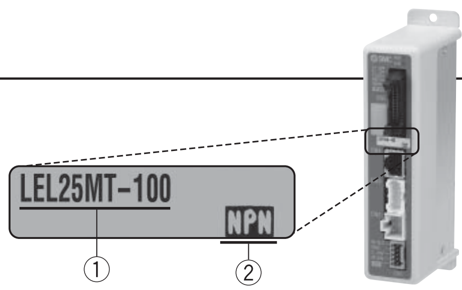
The actuator and controller are provided as a set.

Confirm that the combination of the controller and the actuator is correct.

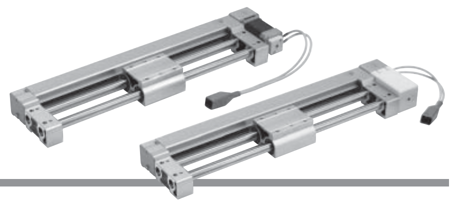
<Check the following before use.>

① Check the actuator label for model number. This matches the controller.

② Check Parallel I/O configuration matches (NPN or PNP).



* Refer to the operation manual for using the products. Please download it via our website, http://www.smcworld.com



❼ Actuator cable length [m]

Nil	Without cable	**8**	8*
1	1.5	**A**	10*
3	3	**B**	15*
5	5	**C**	20*

* Produced upon receipt of order (Robotic cable only)
Refer to the specifications Note 2) on page 149.

❽ Controller type*

Nil	Without controller	
6N	**LECP6** (Step data input type)	NPN
6P		PNP
1N	**LECP1** (Programless type)	NPN
1P		PNP
MJ	**LECPMJ** (CC-Link direct input type)	—

* For details about controller and compatible motor, refer to the compatible controller below.

❾ I/O cable length [m]*1, Communication plug

Nil	Without cable (Without communication plug connector)*2
1	1.5*
3	3*
5	5*
S	Straight type communication plug connector*2
T	T-branch type communication plug connector*2

*1 When "Without controller" is selected for controller types, I/O cable length cannot be selected.
*2 For the LECPMJ, only "Nil", "S" and "T" are selectable since I/O cable is not included.

❿ Controller mounting

Nil	Screw mounting
D	DIN rail mounting*

* DIN rail is not included. Order it separately.

⓫ Made to Order

Nil	Standard product
X5	With magnet/switch rail

Compatible Controller

Type	**Step data input type** 	**CC-Link direct input type** 	**Programless type** 
Series	**LECP6**	**LECPMJ**	**LECP1**
Features	Value (Step data) input Standard controller	CC-Link direct input	Capable of setting up operation (step data) without using a PC or teaching box
Compatible motor	Step motor (Servo/24 VDC)		
Maximum number of step data	64 points		14 points
Power supply voltage	24 VDC		
Reference page	Page 551	Page 591	Page 567

Specifications

Step Motor (Servo/24 VDC)

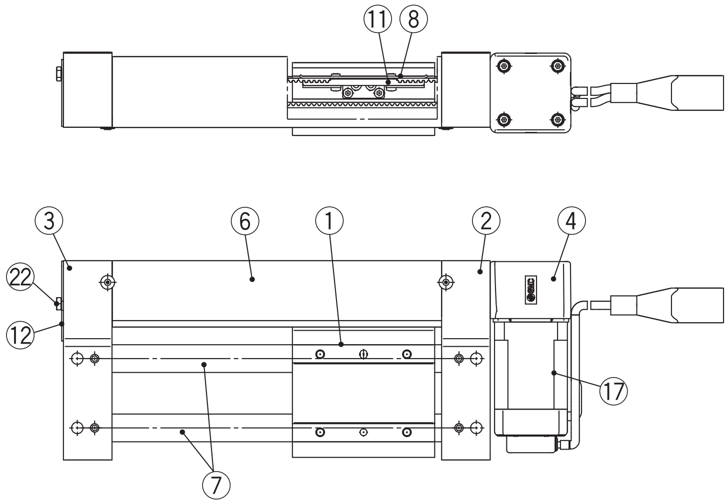
	Model		LEL25M	LEL25L
Actuator specifications	**Stroke [mm]** Note1)		(100), (200), 300, 400, 500, 600 (700), (800), (900), (1000)	
	Work load [kg] Note 2)	Horizontal (Wall mounting)	3 (2.5)	5 (5)
	Speed [mm/s] Note 2)		48 to 500	48 to 1000
	Max. acceleration/deceleration [mm/s²]		3000	
	Positioning repeatability [mm]		±0.08	
	Lost motion [mm] Note 3)		0.1 or less	
	Equivalent lead [mm]		48	
	Impact/Vibration resistance [m/s²] Note 4)		50/20	
	Actuation type		Belt	
	Guide type		Sliding bearing	Ball bushing bearing
	Allowable external force [N] Note 5)		5	
	Operating temperature range [°C]		5 to 40	
	Operating humidity range [%RH]		90 or less (No condensation)	
Electric specifications	**Motor size**		□42	
	Motor type		Step motor (Servo/24 VDC)	
	Encoder		Incremental A/B phase (800 pulse/rotation)	
	Rated voltage [V]		24 VDC ±10%	
	Power consumption [W] Note 6)		32	
	Standby power consumption when operating [W] Note 7)		16	
	Max. instantaneous power consumption [W] Note 8)		60	
Lock unit specifications	**Type** Note 9)		Non-magnetizing lock	
	Holding force [N]		19	
	Power consumption [W] Note 10)		5	
	Rated voltage [V]		24 VDC ±10%	

Note 1) Strokes shown in ( ) are produced upon receipt of order. Please consult with SMC as all non-standard and non-made-to-order strokes are produced as special orders.
Note 2) Speed changes according to the work load. Check "Speed–Work Load Graph (Guide)" on page 146. The work load changes according to the stroke and work load mounting condition.
Check "Dynamic Allowable Moment" graph on page 144. Furthermore, if the cable length exceeds 5 m, then it will decrease by up to 10% for each 5 m.
Note 3) A reference value for correcting an error in reciprocal operation.
Note 4) Impact resistance: No malfunction occurred when the actuator was tested with a drop tester in both the stroke direction and a perpendicular direction to the stroke. (The test was performed with the actuator in the initial state.)
Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz, when the actuator was tested in both stroke direction and a perpendicular direction to the stroke. (The test was performed with the actuator in the initial state.)
Note 5) Allowable external resistance is the allowable resistance when flexible moving tube or similar is used.
Note 6) The power consumption (including the controller) is for when the actuator is operating.
Note 7) The standby power consumption when operating (including the controller) is for when the actuator is stopped in the set position during operation.
Note 8) The maximum instantaneous power consumption (including the controller) is for when the actuator is operating. This value can be used for the selection of the power supply.
Note 9) With lock only
Note 10) For an actuator with lock, add the power consumption for the lock.

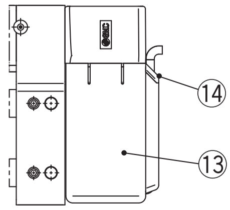
Actuator Product Weight

Stroke [mm]		(100)	(200)	300	400	500	600	(700)	(800)	(900)	(1000)
Product weight [kg]	**LEL25M**	2.13	2.47	2.82	3.17	3.52	3.87	4.21	4.56	4.91	5.26
	LEL25L	2.38	2.72	3.07	3.42	3.77	4.12	4.47	4.82	5.17	5.52
Additional weight with lock [kg]		0.26									
Additional weight with cover [kg]		0.04									

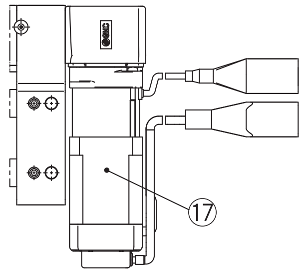
Construction

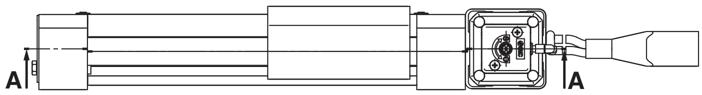


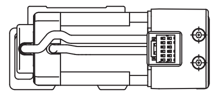
Motor option:
With motor cover



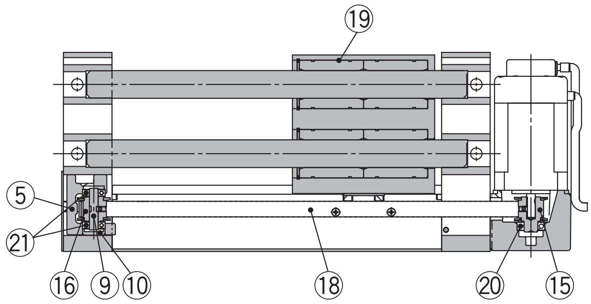
Motor option:
With lock



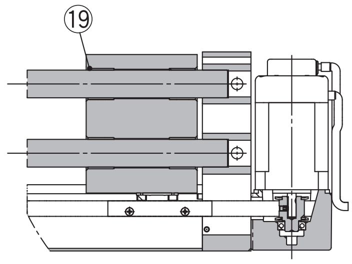




A-A (LEL25LT-□)



A-A (LEL25MT-□)

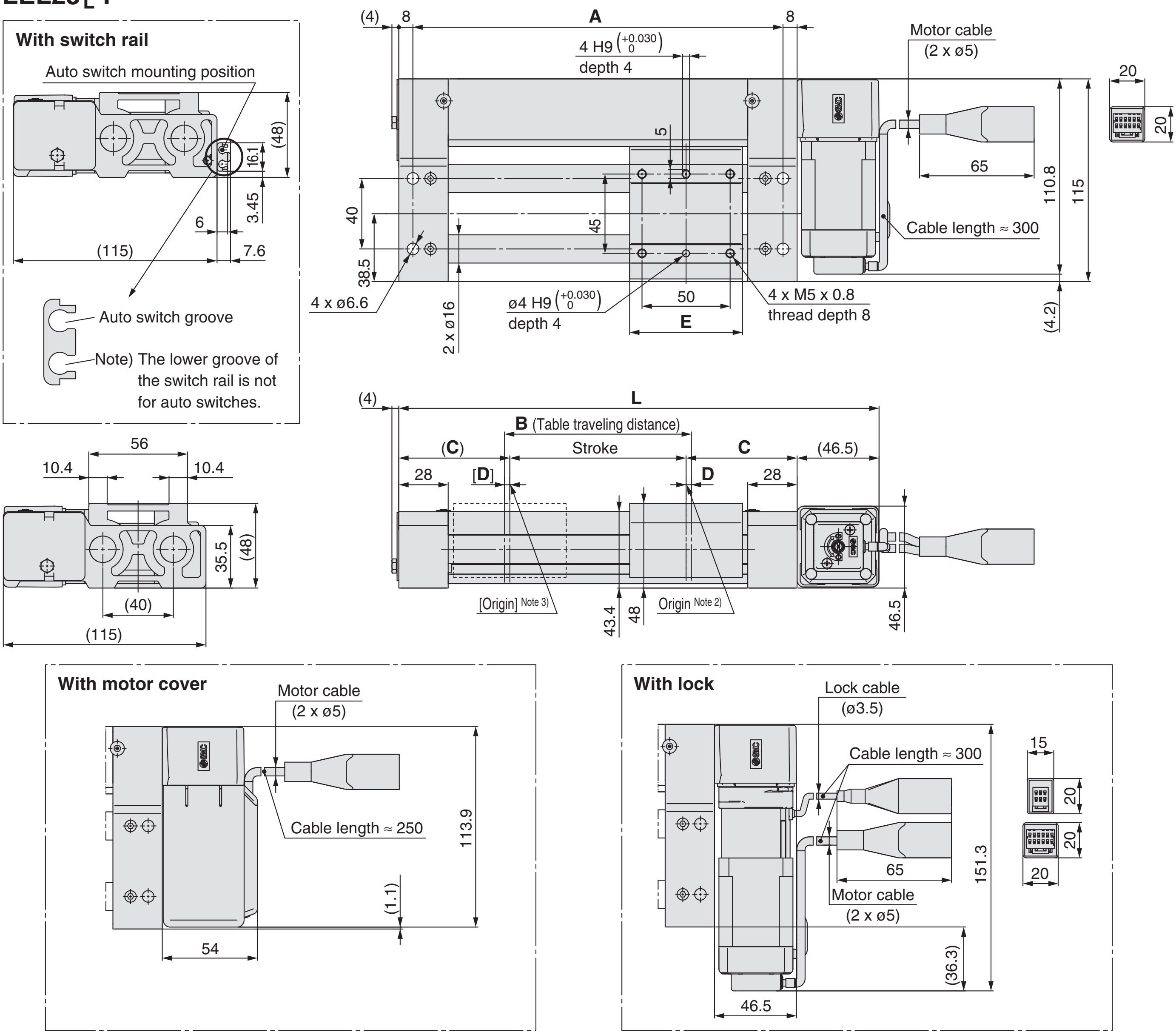


Component Parts

No.	Description	Material	Note
1	**Table**	Aluminum alloy	Anodized
2	**Motor end plate**	Aluminum alloy	Anodized
3	**End plate**	Aluminum alloy	Anodized
4	**Motor mount**	Aluminum die-cast	Painting
5	**Pulley holder**	Aluminum alloy	
6	**Belt cover**	Aluminum alloy	Anodized
7	**Guide rod**	Carbon steel	Hard chrome plating
8	**Belt holder**	Carbon steel	Chromating
9	**Pulley shaft**	Stainless steel	
10	**Spacer**	Aluminum alloy	
11	**Belt stopper**	Aluminum alloy	
12	**Tension plate**	Aluminum alloy	Anodized
13	**Motor cover**	Synthetic resin	“With motor cover” only
14	**Grommet**	Synthetic resin	“With motor cover” only
15	**Motor pulley**	Aluminum alloy	Anodized
16	**End pulley**	Aluminum alloy	Anodized
17	**Motor**	—	
18	**Belt**	—	
19	**Bushing**	—	
	Ball bushing bearing	—	
20	**Bearing**	—	
21	**Bearing**	—	
22	**Hexagon bolt**	Carbon steel	Chromating

Dimensions

LEL25$^{M}_{L}$T



Note 1) Distance within which the table can move when it returns to origin. Make sure a workpiece mounted on the table does not interfere with the workpieces and facilities around the table.
Note 2) Position after return to origin.
Note 3) [ ] for when the direction of return to origin has changed.

[mm]

Model	L	L*	A	B	C	D	E
LEL25MT-100□-□□□□□	272.5	280	210	106	63	3	64
LEL25MT-200□-□□□□□	372.5	380	310	206			
LEL25MT-300□-□□□□□	472.5	480	410	306			
LEL25MT-400□-□□□□□	572.5	580	510	406			
LEL25MT-500□-□□□□□	672.5	680	610	506			
LEL25MT-600□-□□□□□	772.5	780	710	606			
LEL25MT-700□-□□□□□	872.5	880	810	706			
LEL25MT-800□-□□□□□	972.5	980	910	806			
LEL25MT-900□-□□□□□	1072.5	1080	1010	906			
LEL25MT-1000□-□□□□□	1172.5	1180	1110	1006			
LEL25LT-100□-□□□□□	292.5	300	230	108	73	4	82
LEL25LT-200□-□□□□□	392.5	400	330	208			
LEL25LT-300□-□□□□□	492.5	500	430	308			
LEL25LT-400□-□□□□□	592.5	600	530	408			
LEL25LT-500□-□□□□□	692.5	700	630	508			
LEL25LT-600□-□□□□□	792.5	800	730	608			
LEL25LT-700□-□□□□□	892.5	900	830	708			
LEL25LT-800□-□□□□□	992.5	1000	930	808			
LEL25LT-900□-□□□□□	1092.5	1100	1030	908			
LEL25LT-1000□-□□□□□	1192.5	1200	1130	1008			

∗ With motor cover

Solid State Auto Switch Direct Mounting Style
D-M9N(V)/D-M9P(V)/D-M9B(V) CE RoHS

Refer to SMC website for the details about products conforming to the international standards.

Grommet

- 2-wire load current is reduced (2.5 to 40 mA).
- Flexibility is 1.5 times greater than the former model (SMC comparison).
- Using flexible cable as standard.

⚠Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

Auto Switch Specifications

PLC: Programmable Logic Controller

D-M9□, D-M9□V (With indicator light)

Auto switch model	D-M9N	D-M9NV	D-M9P	D-M9PV	D-M9B	D-M9BV
Electrical entry	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 µA or less at 24 VDC				0.8 mA or less	
Indicator light	Red LED lights up when turned ON.					
Standards	CE marking, RoHS					

Oilproof Heavy-duty Lead Wire Specifications

Auto switch model		D-M9N□	D-M9P□	D-M9B□
Sheath	Outside diameter [mm]	2.7 x 3.2 (ellipse)		
Insulator	Number of cores	3 cores (Brown/Blue/Black)		2 cores (Brown/Blue)
	Outside diameter [mm]	ø0.9		
Conductor	Effective area [mm²]	0.15		
	Strand diameter [mm]	ø0.05		
Minimum bending radius [mm] (Reference value)		20		

Note 1) Refer to the Best Pneumatics No. 2 for solid state auto switch common specifications.
Note 2) Refer to the Best Pneumatics No. 2 for lead wire lengths.

Weight

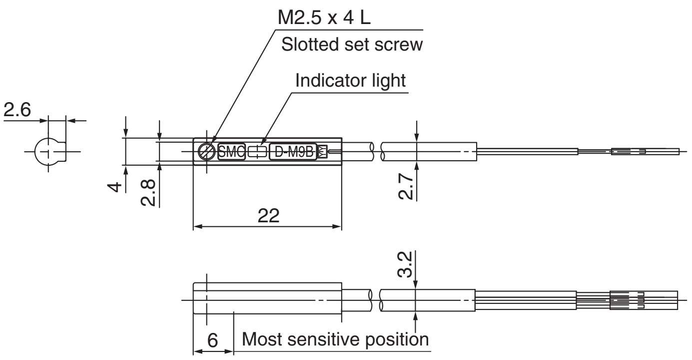
[g]

Auto switch model		D-M9N(V)	D-M9P(V)	D-M9B(V)
Lead wire length	0.5 m (**Nil**)	8		7
	1 m (**M**)	14		13
	3 m (**L**)	41		38
	5 m (**Z**)	68		63

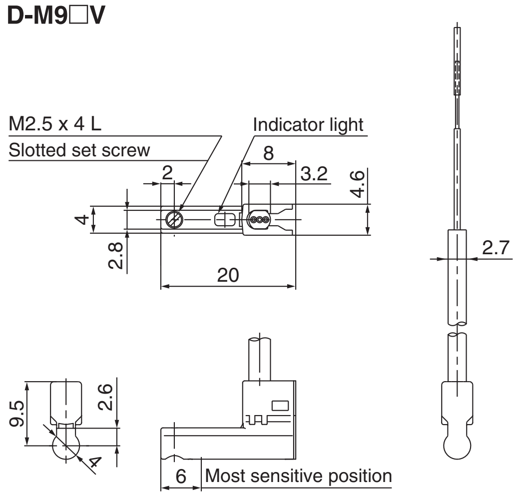
Dimensions

[mm]

D-M9□



D-M9□V



2-Color Indication Solid State Auto Switch Direct Mounting Style
D-M9NW(V)/D-M9PW(V)/D-M9BW(V) CE RoHS

Refer to SMC website for the details about products conforming to the international standards.

Grommet

- **2-wire load current is reduced (2.5 to 40 mA).**
- **Flexibility is 1.5 times greater than the former model (SMC comparison).**
- **Using flexible cable as standard.**
- **The optimum operating range can be determined by the color of the light. (Red → Green ← Red)**

⚠Caution

Precautions

Fix the auto switch with the existing screw installed on the auto switch body. The auto switch may be damaged if a screw other than the one supplied is used.

Auto Switch Specifications

PLC: Programmable Logic Controller

D-M9□W, D-M9□WV (With indicator light)						
Auto switch model	**D-M9NW**	**D-M9NWV**	**D-M9PW**	**D-M9PWV**	**D-M9BW**	**D-M9BWV**
Electrical entry	In-line	Perpendicular	In-line	Perpendicular	In-line	Perpendicular
Wiring type	3-wire				2-wire	
Output type	NPN		PNP		—	
Applicable load	IC circuit, Relay, PLC				24 VDC relay, PLC	
Power supply voltage	5, 12, 24 VDC (4.5 to 28 V)				—	
Current consumption	10 mA or less				—	
Load voltage	28 VDC or less		—		24 VDC (10 to 28 VDC)	
Load current	40 mA or less				2.5 to 40 mA	
Internal voltage drop	0.8 V or less at 10 mA (2 V or less at 40 mA)				4 V or less	
Leakage current	100 μA or less at 24 VDC				0.8 mA or less	
Indicator light	Operating range ·········· Red LED lights up. Optimum operating range ·········· Green LED lights up.					
Standards	CE marking, RoHS					

Oilproof Flexible Heavy-duty Lead Wire Specifications

Auto switch model		**D-M9NW□**	**D-M9PW□**	**D-M9BW□**
Sheath	Outside diameter [mm]	2.7 x 3.2 (ellipse)		
Insulator	Number of cores	3 cores (Brown/Blue/Black)		2 cores (Brown/Blue)
	Outside diameter [mm]	ø0.9		
Conductor	Effective area [mm²]	0.15		
	Strand diameter [mm]	ø0.05		
Minimum bending radius [mm] (Reference value)		20		

Note 1) Refer to the Best Pneumatics No. 2 for solid state auto switch common specifications.
Note 2) Refer to the Best Pneumatics No. 2 for lead wire lengths.

Weight

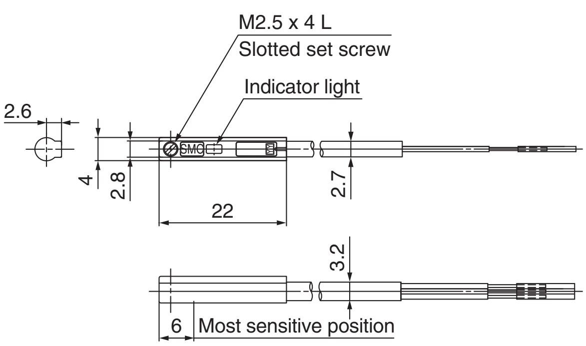
[g]

Auto switch model		**D-M9NW(V)**	**D-M9PW(V)**	**D-M9BW(V)**
Lead wire length	0.5 m (**Nil**)	8		7
	1 m (**M**)	14		13
	3 m (**L**)	41		38
	5 m (**Z**)	68		63

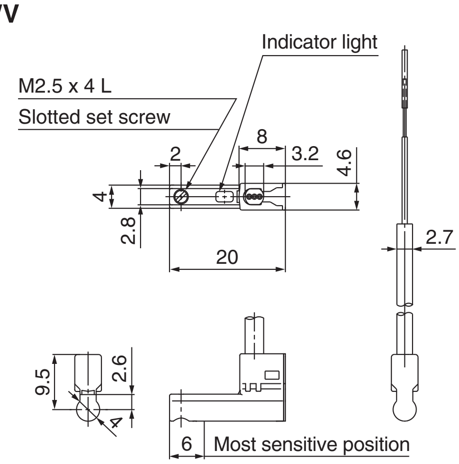
Dimensions

[mm]

D-M9□W



D-M9□WV



Electric Actuator/Guide Rod Slider Specific Product Precautions 1

Be sure to read this before handling. Refer to page 906 for Safety Instructions. For Electric Actuator Precautions, refer to pages 907 to 912, or "Handling Precautions for SMC Products" and the Operation Manual on SMC website, http://www.smcworld.com

Design

⚠Caution

1. Do not apply a load in excess of the specification limits.
Select a suitable actuator by work load and allowable moment. If the product is used outside of the specification limits, the eccentric load applied to the guide will be excessive and have adverse effects such as creating play on the guide, degrading accuracy and shortening the life of the product.

2. Do not use the product in applications where excessive external force or impact force is applied to it.
This can cause failure.

3. Because of the guide mechanism type, vibration that comes from an external source may be introduced into the workpiece during operation. Do not use this product in a location where vibration is not allowed.

Handling

⚠Caution

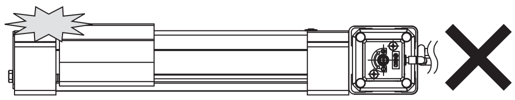
1. Set [In position] in the step data to at least 1.
Otherwise, completion signal of in position may not be output.

2. INP output signal
1) Positioning operation
When the product comes within the set range by step data [In position], the INP output signal will turn on.
Initial value: Set to [1] or higher.

Handling

⚠Caution

3. Never hit at the stroke end except during return to origin.
When incorrect instructions are inputted, such as using the product outside of the specification limits or operation outside of actual stroke through changes in the controller/driver setting and/or origin position, the table may collide against the stroke end of the actuator. Check these points before use.
If the table collides against the stroke end of the actuator, the guide, belt or internal stopper can be broken. This may lead to abnormal operation.



4. The moving force should be the initial value (100%).
If the moving force is set below the initial value, it may cause an alarm.

5. The actual speed of this actuator is affected by the work load.
When selecting a product, check the catalog for the instructions regarding selection.

6. Do not apply a load, impact or resistance in addition to the transferred load during return to origin.
Additional force will cause the displacement of the origin position since it is based on detected motor torque.

7. Do not dent, scratch or cause other damage to the body and table mounting surfaces.
This may cause unevenness in the mounting surface, play in the guide or an increase in the sliding resistance.

8. Do not apply strong impact or an excessive moment while mounting a workpiece.
If an external force over the allowable moment is applied, it may cause play in the guide or an increase in the sliding resistance.

9. Keep the flatness of the mounting surface 0.2 mm or less.
Unevenness of a workpiece or base mounted on the body of the product may cause play in the guide and an increase in the sliding resistance.

10. When mounting the product, keep a 40 mm or longer diameter for bends in the cable.

11. Do not hit the table with the workpiece in the positioning operation and positioning range.

12. Hold by the end plates when moving the body. Do not hold the belt cover.

Series LEL
Electric Actuator/Guide Rod Slider Specific Product Precautions 2

Be sure to read this before handling. Refer to page 906 for Safety Instructions. For Electric Actuator Precautions, refer to pages 907 to 912, or "Handling Precautions for SMC Products" and the Operation Manual on SMC website, http://www.smcworld.com

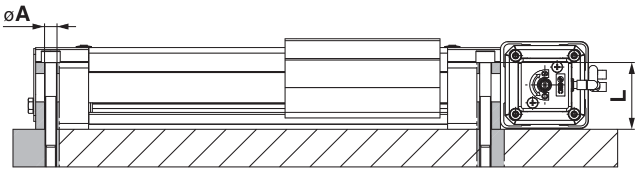
Handling

⚠Caution

13. When mounting the product, use screws with adequate length and tighten them with adequate torque.

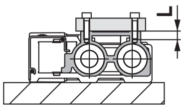
Tightening the screws with a higher torque than recommended may cause a malfunction, whilst the tightening with a lower torque can cause the displacement of the mounting position or in extreme conditions the actuator could become detached from its mounting position.

Body fixed



Model	Screw size	Max. tightening torque [N·m]	øA [mm]	L [mm]
LEL25	M6	5.2	6.6	35.5

Workpiece fixed



Model	Screw size	Max. tightening torque [N·m]	L (Max. screw-in depth) [mm]
LEL25	M5 x 0.8	3	8

To prevent the workpiece retaining screws from touching the body, use screws that are 0.5 mm or shorter than the maximum screw-in depth. If long screws are used, they can touch the body and cause a malfunction.

14. Do not operate by fixing the table and moving the actuator body.

15. The belt drive actuator cannot be used vertically for applications.

16. Check the specifications for the minimum speed of each actuator.

Otherwise, unexpected malfunctions, such as knocking, may occur.

17. In the case of the belt drive actuator, vibration may occur during operation at speeds within the actuator specifications, this could be caused by the operating conditions. Change the speed setting to a speed that does not cause vibration.

Maintenance

⚠Warning

Maintenance frequency

Perform maintenance according to the table below.

Frequency	Appearance check	Internal check	Belt check
Inspection before daily operation	○	—	—
Inspection every 6 months/1000 km/ 5 million cycles*	○	○	○

* Select whichever comes first.

• Items for visual appearance check

1. Loose set screws, Abnormal dirt
2. Check of flaw and cable joint
3. Vibration, Noise

• Items for internal check

1. Lubricant condition on moving parts.
2. Loose or mechanical play in fixed parts or fixing screws.

• Items for belt check

Stop operation immediately and replace the belt when belt appear to be below. Further, ensure your operating environment and conditions satisfy the requirements specified for the product.

a. Tooth shape canvas is worn out.
Canvas fiber becomes fuzzy. Rubber is removed and the fiber becomes whitish. Lines of fibers become unclear.

b. Peeling off or wearing of the side of the belt
Belt corner becomes round and frayed thread sticks out.

c. Belt partially cut
Belt is partially cut. Foreign matter caught in teeth other than cut part causes flaw.

d. Vertical line of belt teeth
Flaw which is made when the belt runs on the flange.

e. Rubber back of the belt is softened and sticky.

f. Crack on the back of the belt