Pneumatic Toggle Grippers OG 2-Finger

OG2 is a two-finger toggle gripper with a high grip force and non-reversible mechanism, suitable for heavy industrial applications.

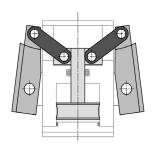
Advantages

- High energy density.
- Capability to grip parts in opening and closing mode.
- Driving mechanism guided along the entire stroke giving high stability and precision.
- Large surface for finger mounting to guarantee extremely safe clamping of the workpiece.
- The toggle mechanism provides non-reversible gripping in the opening and closing positions even without air pressure
- Air supply via screw connection.

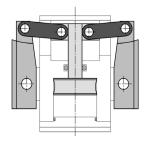




Open/Close Diagram

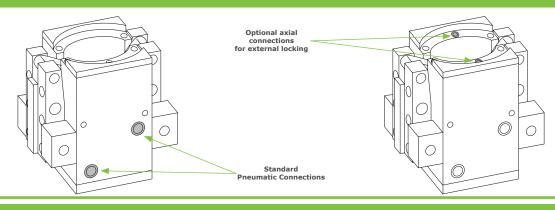




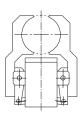


CLOSED

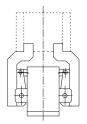
Pneumatic Feed



Gripping Diagram



External Clamping



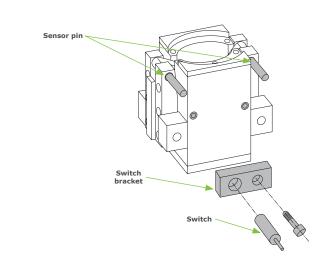
Internal Clamping

Guidelines for the selection of a gripper model
Selection of the correct gripper model depends on the workpiece's
weight, the friction coefficient between the fingers and the workpiece
and the required motion of the application.
Due to inertial forces associated with motion, we recommend that the
holding force of the gripper model should be from 10 to 20 times the

workpiece's weight.

If the application presents high acceleration/deceleration or impacts during the motion,
then a further safety margin should be considered.

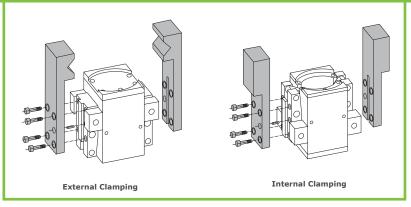
Control Diagram



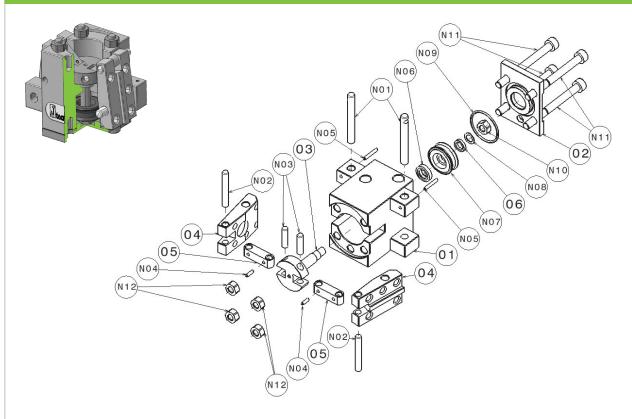
Mounting

Axial Mounting Axial Mounting
Bottom fixing Top fixing

Fingers Mounting



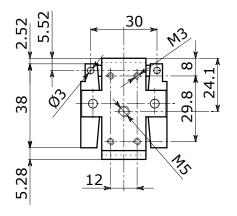
Construction Diagram

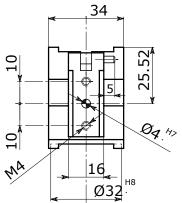


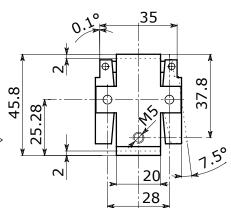
Nr.	Description	Material
01	BODY	Aluminum Alloy
02	CAP	Aluminum Alloy
03	DRIVE HUB	Chrome Molybdenum Steel
04	JAW	Chrome Molybdenum Steel
05	TOGGLE LEVER	Chrome Molybdenum Steel
06	RING	Steel
N01	PIN	Chrome Molybdenum Steel
N02	KNUCKLE PIN	Chrome Molybdenum Steel
N03	KNUCKLE PIN	Chrome Molybdenum Steel
N04	SAFETY PIN	Steel
N05	SAFETY PIN	Steel
N06	SHAFT SEAL	NBR
N07	PISTON SEAL	NBR + Steel
N08	WASHER	Steel
N09	CAP SEAL	NBR
N10	NUT	Steel
N11	SCREW	Steel
N12	NUT	Steel

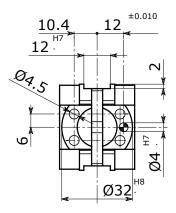


05510







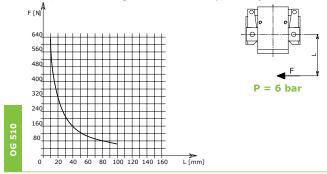


		OG 510
Stroke per jaw	0	7.5
Fluid consumption double stroke	cm³ in³	2.7 0.2
Closing moment per jaw @ 6 bar	Nm in lb	6.5 58
Total closing moment @ 6 bar	Nm in lb	13 115
Recommended workpiece weight	Kg Ib	0.31 0.70
Weight	Kg Ib	0.17 0.37
Repeat accuracy	mm in	± 0.05 ± 0.002

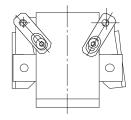
^{*} Recommended workpiece weight is calculated for force-fit gripping with a coefficient of static friction of 0.15 and a safety factor of 3 against workpiece slippage. Opening Pressure 2 - 8 bar (29 - 116 psi)
Working Temperature 5 - 60 °C (41 - 140 °F)
Noise Emission (Sound Pressure) ≤ 70 db(A) in any direction

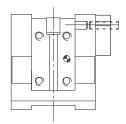
Clamping Force Diagram

 $\textbf{Note: "L"} \ \ \text{value, where the diagram's line ends, represents jaws' maximum length.}$



F = True clamping force per jaw - L = Reading distance Values read in toggle position (0°)





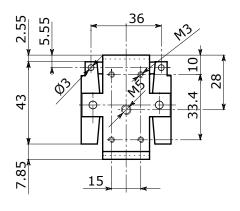


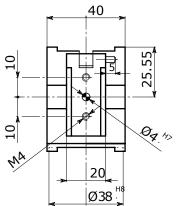


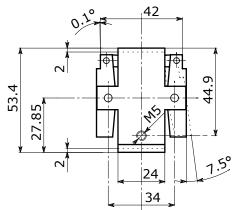
			Open/Closed control									
		A	В	С	D	E	F	G	н	J	K	
OG 510	mm in	22 0.87	7 0.28	8.5 0.33	6.5 0.26	9 0.35	3.5 0.14	7 0.28	M5x0.5	М3	8 0.31	

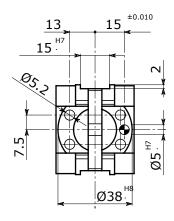


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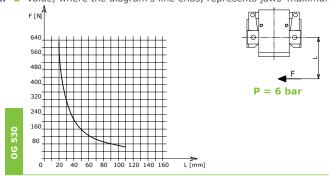


		OG 530
Stroke per jaw	0	7.5
Fluid consumption double stroke	cm³ in³	5 0.3
Closing moment per jaw @ 6 bar	Nm in lb	13 115
Total closing moment @ 6 bar	Nm in lb	26 230
Recommended workpiece weight	Kg Ib	0.62 1.40
Weight	Kg Ib	0.28 0.62
Repeat accuracy	mm in	± 0.05 ± 0.002

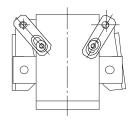
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Working Temperature 5 - 60 °C (41 - 140 °F)
Noise Emission (Sound Pressure) ≤ 70 db(A) in any direction

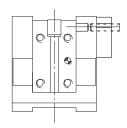
Clamping Force Diagram

 $\textbf{Note: "L"} \ \ \text{value, where the diagram's line ends, represents jaws' maximum length.}$



F = True clamping force per jaw - L = Reading distanceValues read in toggle position (0°)





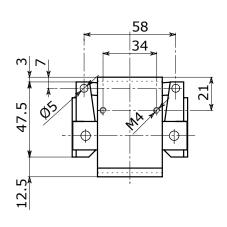


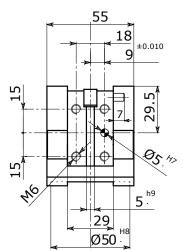
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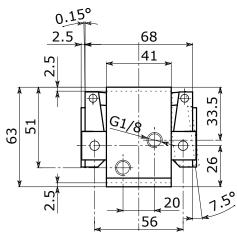
			Open/Closed control									
		A	В	С	D	E	F	G	н	J	K	
OG 530	mm in	23.5 0.93	7 0.28	10 0.39	6.5 0.26	9 0.35	3.5 0.14	7 0.28	M5x0.5	М3	8 0.31	

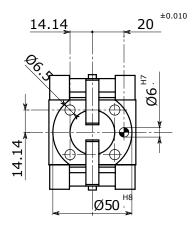


06 550-7.50







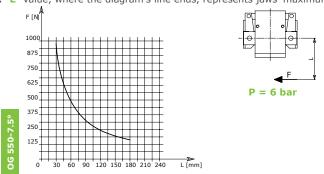


		OG 550-7.5°
Stroke per jaw	0	7.5
Fluid consumption double stroke	cm³ in³	11.5 0.7
Closing moment per jaw @ 6 bar	Nm in lb	30 266
Total closing moment @ 6 bar	Nm in lb	60 532
Recommended workpiece weight	Kg Ib	1.43 3.10
Weight	Kg lb	0.63 1.38
Repeat accuracy	mm in	± 0.05 ± 0.002

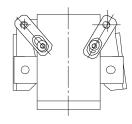
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Working Temperature 5 - 60 °C (41 - 140 °F)
Noise Emission (Sound Pressure) ≤ 70 db(A) in any direction

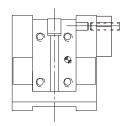
Clamping Force Diagram

 $\textbf{Note: "L"} \ \ \text{value, where the diagram's line ends, represents jaws' maximum length.}$



 $\mathbf{F}=$ True clamping force per jaw - $\mathbf{L}=$ Reading distance Values read in toggle position (0°)





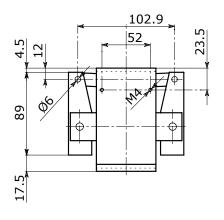


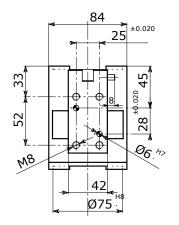


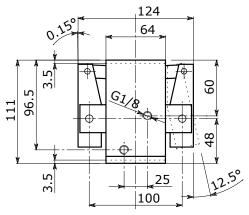
			Open/Closed control									
		A	В	С	D	E	F	G	н	J	K	
OG 550-7.5°	mm in	32 1.26	8.5 0.33	17 0.67	6.5 0.26	10 0.39	4.5 0.18	9 0.35	M5x0.5	М3	10 0.39	

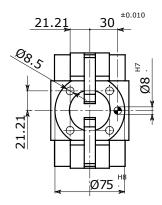


OG 550-12.5°









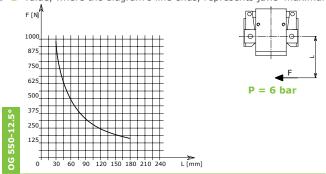


		OG 550-12.5°
Stroke per jaw	0	12.5
Fluid consumption double stroke	cm³ in³	11.5 0.7
Closing moment per jaw @ 6 bar	Nm in lb	30 266
Total closing moment @ 6 bar	Nm in lb	60 532
Recommended workpiece weight	Kg Ib	1.43 3.10
Weight	Kg Ib	0.72 1.58
Repeat accuracy	mm in	± 0.05 ± 0.002

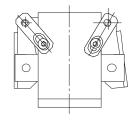
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Working Temperature 5 - 60 °C (41 - 140 °F)
Noise Emission (Sound Pressure) ≤ 70 db(A) in any direction

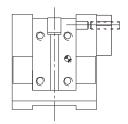
Clamping Force Diagram

 $\textbf{Note: "L"} \ \ \text{value, where the diagram's line ends, represents jaws' maximum length.}$



F = True clamping force per jaw - L = Reading distance Values read in toggle position (0°)





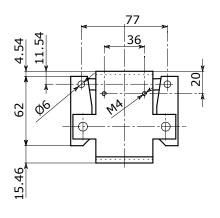


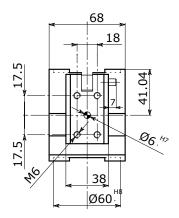


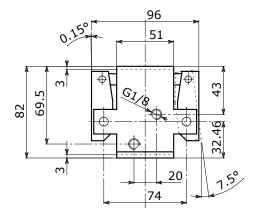
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		A	В	С	D	E	F	G	н	J	K
OG 550-12.5°	mm in	33.5 1.32	8.5 0.33	18.5 0.73	6.5 0.26	10 0.39	4.5 0.18	9 0.35	M5x0.5	М3	10 0.39

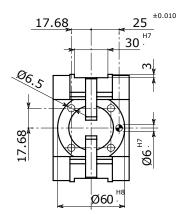


05565











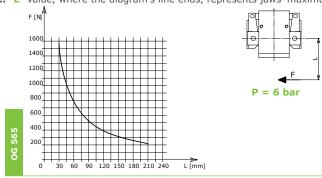
TECHNICAL DATA OG 565 Stroke per jaw 7.5 26 Fluid consumption cm³ double stroke in³ 1.6 Closing moment per jaw 48 Nm @ 6 bar in Ib 425 Total closing moment Nm 96 @ 6 bar 850 in lb 2.29 Recommended Kg workpiece weight Ιb 5.00 1.20 Kg Weight 2.64

Clamping Force Diagram

Repeat accuracy

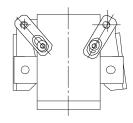
mm

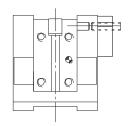
 $\textbf{Note: "L"} \ \ \text{value, where the diagram's line ends, represents jaws' maximum length.}$



F = True clamping force per jaw - L = Reading distance Values read in toggle position (0°)

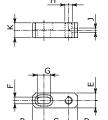
Open-Closed Control Position with External Switches





 ± 0.05

 ± 0.002



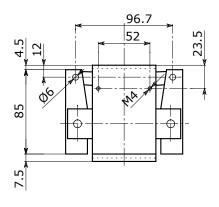
			open/closed control								
		Α	В	С	D	E	F	G	н	J	K
OG 565	mm in	35 1.38	8.5 0.33	20 0.79	6.5 0.26	10 0.39	4.5 0.18	10 0.39	M5x0.5	М3	10 0.39

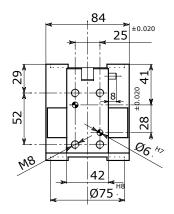
Open/Closed control

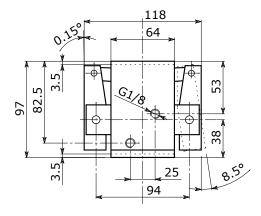
^{*} Recommended workpiece weight is calculated for force-fit gripping with a coefficient of static friction of 0.15 and a safety factor of 3 against workpiece slippage. Opening Pressure 2 - 8 bar (29 - 116 psi)
Working Temperature 5 - 60 °C (41 - 140 °F)
Noise Emission (Sound Pressure) ≤ 70 db(A) in any direction

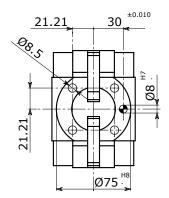


06570-8.5°









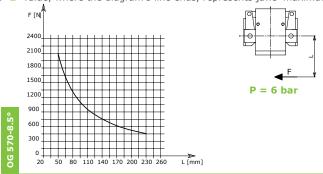


		OG 570-8.5°
Stroke per jaw	0	8.5
Fluid consumption double stroke	cm³ in³	48.5 3
Closing moment per jaw @ 6 bar	Nm in lb	105 929
Total closing moment @ 6 bar	Nm in lb	210 1859
Recommended workpiece weight	Kg Ib	5.00 11.00
Weight	Kg Ib	2.55 5.61
Repeat accuracy	mm in	± 0.05 ± 0.002

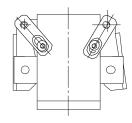
^{*} Recommended workpiece weight is calculated for force-fit gripping with a coefficient of static friction of 0.15 and a safety factor of 3 against workpiece slippage. Opening Pressure 2 - 8 bar (29 - 116 psi)
Working Temperature 5 - 60 °C (41 - 140 °F)
Noise Emission (Sound Pressure) ≤ 70 db(A) in any direction

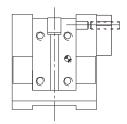
Clamping Force Diagram

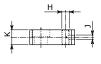
 $\textbf{Note: "L"} \ \ \text{value, where the diagram's line ends, represents jaws' maximum length.}$

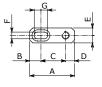


F = True clamping force per jaw - L = Reading distance Values read in toggle position (0°)





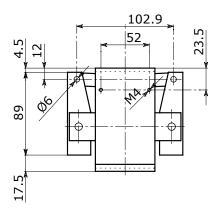


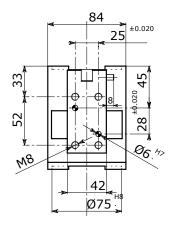


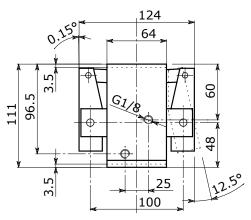
		A	В	С	D	E	F	G	н	J	K
OG 570-8.5°	mm in	39 1.54	10 0.39	22.5 0.89	6.5 0.26	10 0.39	4.5 0.18	12 0.47	M5x0.5	М3	10 0.39

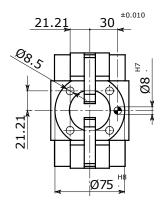


06570-12.5°









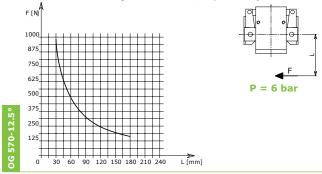


TECHNICAL DATA OG 570-12.5° Stroke per jaw 12.5 65 Fluid consumption cm³ double stroke in³ Closing moment per jaw 105 Nm @ 6 bar in Ib 929 Total closing moment Nm 210 @ 6 bar 1859 in lb 5.00 Recommended Kg workpiece weight Ιb 11.00 2.72 Kg Weight 5.98 ± 0.05 mm

Clamping Force Diagram

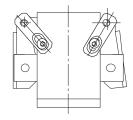
Repeat accuracy

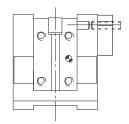
Note: "L" value, where the diagram's line ends, represents jaws' maximum length.



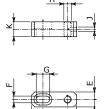
F = True clamping force per jaw - L = Reading distance Values read in toggle position (0°)

Open-Closed Control Position with External Switches





 ± 0.002

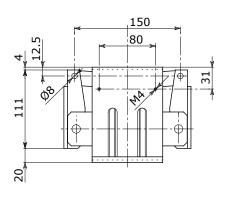


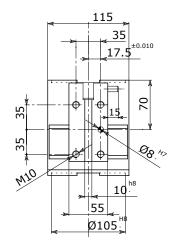
		Open/Closed control									
		A	В	С	D	E	F	G	н	J	К
OG 570-12.5°	mm in	42 1.65	12 0.47	23.5 0.93	6.5 0.26	10 0.39	4.5 0.18	16 0.63	M5x0.5	МЗ	10 0.39

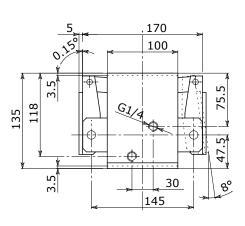
^{*} Recommended workpiece weight is calculated for force-fit gripping with a coefficient of static friction of 0.15 and a safety factor of 3 against workpiece slippage. Opening Pressure 2 - 8 bar (29 - 116 psi)
Working Temperature 5 - 60 °C (41 - 140 °F)
Noise Emission (Sound Pressure) ≤ 70 db(A) in any direction

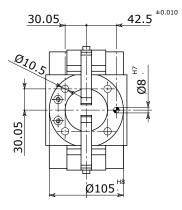


05575-80











OG 575-8° 8 195 11.9 440 3894 880

7789

20.95

46.10 6.50

14.30

Repeat accuracy	mm in	± 0.05 ± 0.002								
Opening Pressure 2 - 8 bar Working Temperature 5 - 60	* Recommended workpiece weight is calculated for force-fit gripping with a coefficient of static friction of 0.15 and a safety factor of 3 against workpiece slippage. Opening Pressure 2 - 8 bar (29 - 116 psi) Working Temperature 5 - 60 °C (41 - 140 °F) Noise Emission (Sound Pressure) ≤ 70 db(A) in any direction									

Clamping Force Diagram

cm³

in³

Nm

in Ib

Nm

in lb

Kg

Kg

Stroke per jaw

double stroke

Recommended

workpiece weight

@ 6 bar

@ 6 bar

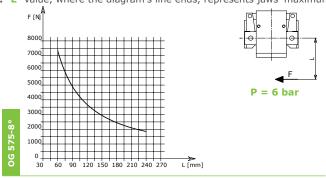
Weight

Fluid consumption

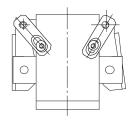
Closing moment per jaw

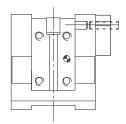
Total closing moment

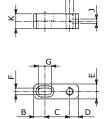
 $\textbf{Note: "L"} \ \ \text{value, where the diagram's line ends, represents jaws' maximum length.}$



F = True clamping force per jaw - L = Reading distance Values read in toggle position (0°)







		open/ closed control									
		A	В	С	D	E	F	G	Н	J	K
OG 575-8°	mm in	56 2.20	12 0.47	35 1.38	9 0.35	12 0.47	4.5 0.18	16 0.63	M8x1	M4	12 0.47

OG 2-Finger Catalogue

[OG 2_catalogue_en] rev. 00_02.2020





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