Pneumatic Parallel Grippers QPGB 3-Finger

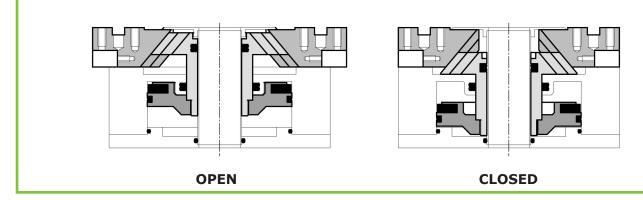
QPGB is a universal three-finger centric gripper, with a hollow center, featuring high reliability and a long service life, suitable for applications that require a center bore, (e.g. for workpiece feed, special sensor systems or optical recognition systems)

Advantages

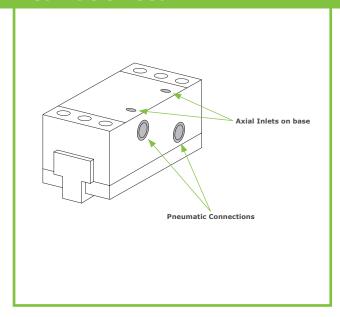
- Robust lightweight housing made of hard-coated aluminum alloy.
- Sturdy T-slot with hardened steel gibs for effective jaw guidance, precise handling, and easy maintenance.
- Central through-hole which can be used for feed through of supply hoses and utilities.
- Mounting from one side in two screw directions for versatile and flexible integration.
- Integrated permanent magnets for direct monitoring of piston movement.
- Slots for mounting and positioning magnetic-field sensors.
- Air supply via hose-free direct connections or fitting screw connections.



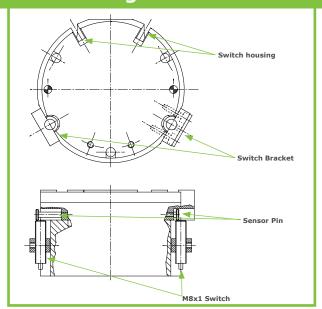
Open/Close Diagram



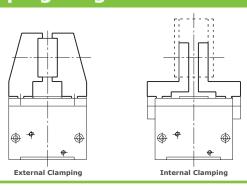
Pneumatic Feed



Control Diagram



Gripping Diagram



Guidelines for the selection of a gripper model

Guidelines for the selection of a gripper model

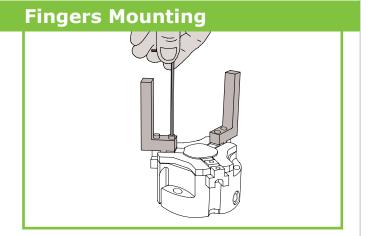
Selection of the correct gripper model depends on the workpiece's weight, the friction coefficient between the fingers and the workpiece and the required motion of the application.

Due to inertial forces associated with motion, we recommend that the holding force of the
gripper model should be from 10 to 20 times the workpiece's weight.

If the application presents high acceleration/deceleration or impacts during the motion,
then a further safety margin should be considered.

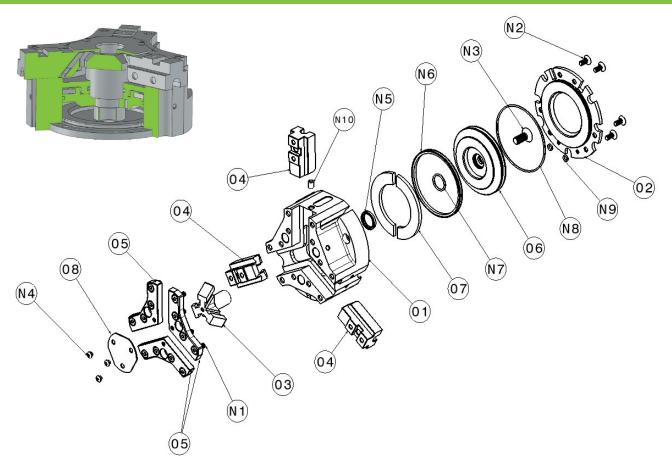
Mounting

Axial Mounting - Bottom Fixing



Construction Diagram

Axial Mounting - Upper Fixing

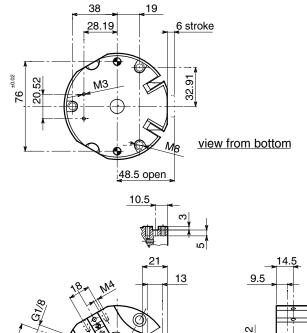


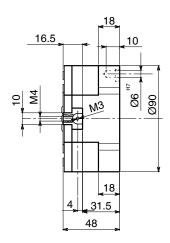
Nr.	Description	Material
01	BODY	Aluminum Alloy
02	CAP	Aluminum Alloy
03	WEDGE HOOK	Chrome Molybdenum Steel
04	JAW	Chrome Molybdenum Steel
05	GIB	Chrome Molybdenum Steel
06	PISTON	Aluminum Alloy
07	MAGNET	Rubber magnet
08	PLATE	Stainless Steel
N1	SCREW	Steel
N2	SCREW	Steel
N3	SCREW	Steel
N4	SCREW	Steel
N5	SHAFT SEAL	NBR
N6	EXT. PISTON SEAL	NBR
N7	INT. PISTON SEAL	NBR
N8	CAP SEAL	NBR
N9	AXIAL FEED SEAL	NBR
N10	LUBRICATOR	Brass

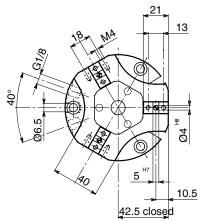
Dimensional Drawing

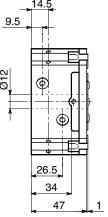


QPGB 309

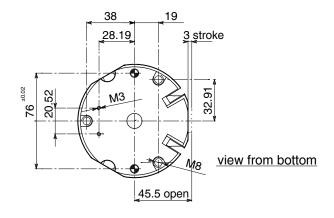








QPGB 309 S

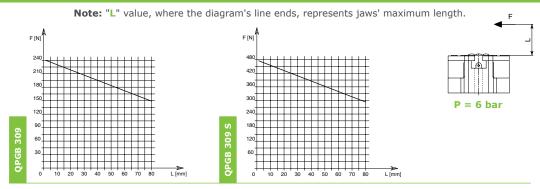


TECHNICAL DATA

		QPGB 309	QPGB 309 S		
Stroke per jaw	mm	6	3		
	in	0.24	0.12		
Fluid consumption double stroke	cm³	28.5	28.5		
	in³	1.74	1.74		
Closing force per jaw	N	230	455		
@ 6 bar	Ib	51.7	102.3		
Opening force per jaw	N	265	530		
@ 6 bar	Ib	59.57	119.15		
Total closing force	N	690	1365		
@ 6 bar	Ib	155.1	306.9		
Total opening force	N	796	1590		
@ 6 bar	Ib	178.95	357.45		
Recommended workpiece weight	Kg	2.30	4.55		
	lb	5.1	10.0		
Weight	Kg	0.85	0.85		
	lb	1.87	1.87		
Repeat accuracy	mm	± 0.01	± 0.01		
	in	± 0.0004	± 0.0004		

^{*} Recommended workpiece weight is calculated for force-fit gripping with a coefficient of static friction of 0.15 and a safety factor of 3 against workpiece slippage. Opening Pressure 2 - 8 bar (29 - 116 psi)
Working Temperature 5 - 60 °C (41 - 140 °F)
Noise Emission (Sound Pressure) <= 70 db(A) in any direction

Clamping Force Diagram

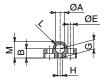


 \mathbf{F} = True clamping force per jaw - \mathbf{L} = Reading distance Values read at a distance L = 10 mm

Open-Closed Control Position with External Switches



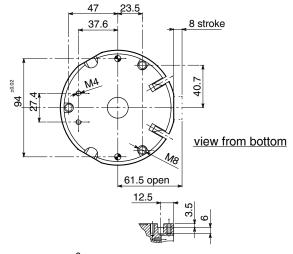
		A	В	С	D	E	F	G
QPG 309/S	mm	8	8	28	10	4.5	18	8
	in	0.31	0.31	1.10	0.39	0.18	0.71	0.31

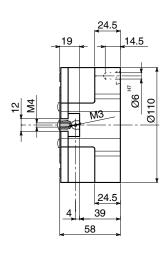


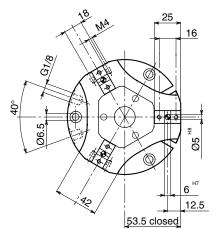
		н	L	М
QPG 309/S	mm in	M4	R6	14 0.55

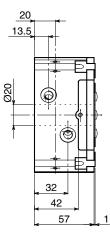
Dimensional Drawing



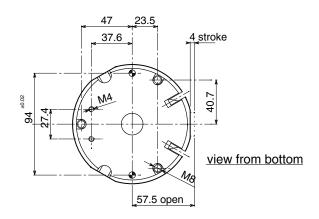








QPGB 311 S

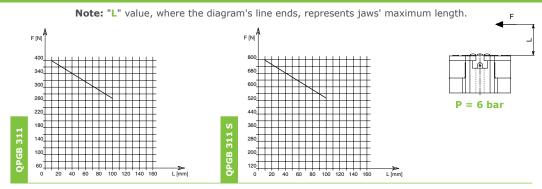


TECHNICAL DATA

		QPGB 311	QPGB 311 S	
Stroke per jaw	mm	8	4	
	in	0.31	0.16	
Fluid consumption double stroke	cm³	66	66	
	in³	4.03	4.03	
Closing force per jaw	N	385	770	
@ 6 bar	Ib	86.5	173.1	
Opening force per jaw	N	452	905	
@ 6 bar	Ib	101.61	203.45	
Total closing force	N	1155	2310	
@ 6 bar	Ib	259.6	519.3	
Total opening force	N	1358	2715	
@ 6 bar	Ib	305.29	610.36	
Recommended workpiece weight	Kg	3.85	7.70	
	lb	8.5	16.9	
Weight	Kg	1.3	1.3	
	lb	2.86	2.86	
Repeat accuracy	mm	± 0.01	± 0.01	
	in	± 0.0004	± 0.0004	

^{*} Recommended workpiece weight is calculated for force-fit gripping with a coefficient of static friction of 0.15 and a safety factor of 3 against workpiece slippage. Opening Pressure 2 - 8 bar (29 - 116 psi)
Working Temperature 5 - 60 °C (41 - 140 °F)
Noise Emission (Sound Pressure) <= 70 db(A) in any direction

Clamping Force Diagram

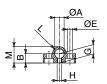


 \mathbf{F} = True clamping force per jaw - \mathbf{L} = Reading distance Values read at a distance L = 20 mm

Open-Closed Control Position with External Switches



		A	В	С	D	E	F	G
QPGB 311/S	mm	8	8	28	10	4.5	18	8
	in	0.31	0.31	1.10	0.39	0.18	0.71	0.31

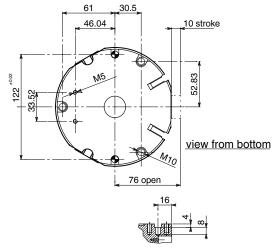


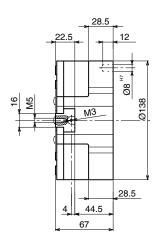
		н	L.	М
QPGB 311/S	mm in	M4	R6	14 0.55

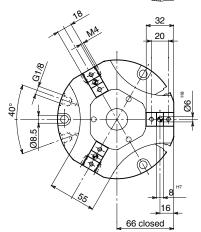
Dimensional Drawing

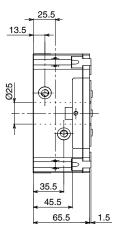




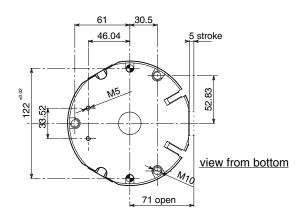








QPGB 313 S

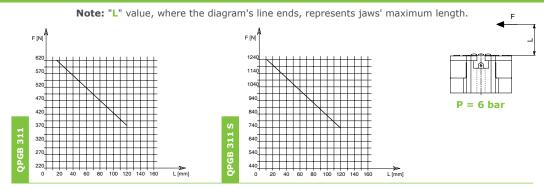


TECHNICAL DATA

		QPGB 313	QPGB 313 S
Stroke per jaw	mm	10	5
	in	0.39	0.20
Fluid consumption double stroke	cm³	130	130
	in³	7.93	7.93
Closing force per jaw	N	610	1200
@ 6 bar	Ib	137.1	269.8
Opening force per jaw	N	716	1415
@ 6 bar	Ib	160.96	318.10
Total closing force	N	1830	3600
@ 6 bar	Ib	411.4	809.3
Total opening force	N	2148	4245
@ 6 bar	Ib	482.89	954.31
Recommended	Kg	6.10	12.00
workpiece weight	lb	13.4	26.4
Weight	Kg	2	2
	lb	4.40	4.40
Repeat accuracy	mm	± 0.01	± 0.01
	in	± 0.0004	± 0.0004

^{*} Recommended workpiece weight is calculated for force-fit gripping with a coefficient of static friction of 0.15 and a safety factor of 3 against workpiece slippage. Opening Pressure 2 - 8 bar (29 - 116 psi)
Working Temperature 5 - 60 °C (41 - 140 °F)
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Clamping Force Diagram

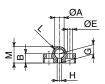


F = True clamping force per jaw - L = Reading distance Values read at a distance L = 20 mm

Open-Closed Control Position with External Switches



		A	В	С	D	E	F	G
QPGB 313/S	mm	8	8	28	10	4.5	18	8
	in	0.31	0.31	1.10	0.39	0.18	0.71	0.31



		н	L	М
QPGB 313/S	mm in	M4	R6	14 0.55

QPGB 3-Finger Catalogue
[QPGB-3_catalogue_en] rev. 00_02.2020





EFFECTO GROUP S.p.A.
Via Roma, 141/143
28017 San Maurizio d'Opaglio (NO) - Italy
Tel. +39 0322 96142 Fax +39 0322 967453
info@effectogroup.com
www.effectogroup.com